

# Randomized Algorithms

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# Constraint Satisfaction Problem

- **variables:**  $x_1, x_2, \dots, x_n \in D$  (domain)
- **constraints:**  $C_1, C_2, \dots, C_m$ 
  - where  $C_i(x_{i_1}, x_{i_2}, \dots) \in \{\text{true}, \text{false}\}$
- CSP **solution**: an assignment of variables satisfying *all* constraints
- examples: SAT, graph colorability, ...
- **existence**: When does a solution exist?
- **search**: How to find a solution?

# The Probabilistic Method

CSP  $C_1, C_2, \dots, C_m$  defined on  $x_1, x_2, \dots, x_n$

- sampling random values of  $x_1, x_2, \dots, x_n$
- **Bad** event  $A_i$ : constraint  $C_i$  is **violated**
- None of the bad events occurs with prob:  $\Pr \left[ \bigwedge_i^m \overline{A_i} \right]$
- **The probabilistic method**: being **good** is possible

$$\Pr \left[ \bigwedge_{i=1}^m \overline{A_i} \right] > 0$$

# Dependency Graph

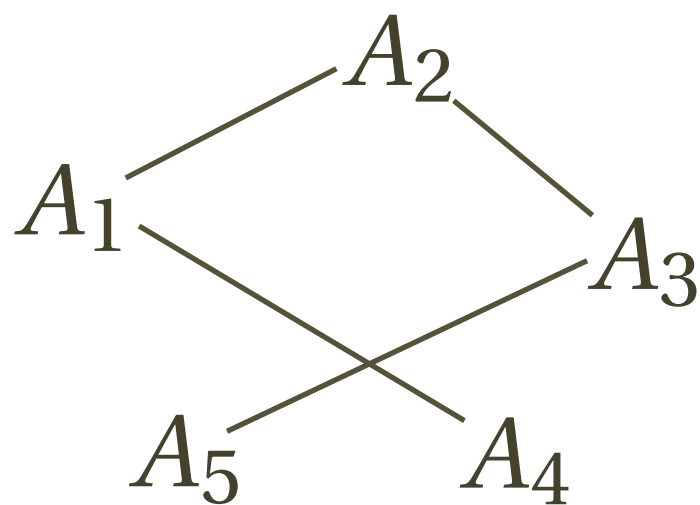
events:  $A_1, A_2, \dots, A_m$

dependency graph:  $D(V, E)$

$$V = \{ 1, 2, \dots, m \}$$

$ij \in E \iff A_i$  and  $A_j$  are *dependent*

$d$  : max degree of dependency graph



$A_1(X_1, X_4)$

$A_4(X_4)$

$A_2(X_1, X_2)$

$A_5(X_3)$

$A_3(X_2, X_3)$

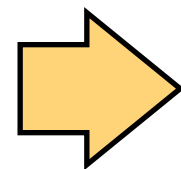
$X_1, \dots, X_4$  mutually independent

events:  $A_1, A_2, \dots, A_m$

each event is independent of all but at most  $d$  other events

### **Lovász Local Lemma (symmetric)**

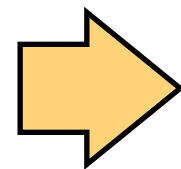
- $\forall i, \Pr[A_i] \leq p$
- $ep(d+1) \leq 1$



$$\Pr \left[ \bigwedge_{i=1}^m \overline{A_i} \right] > 0$$

### **Lovász Local Lemma (general)**

$$\begin{aligned} &\exists \alpha_1, \dots, \alpha_m \in [0, 1) \\ &\forall i, \Pr[A_i] \leq \alpha_i \prod_{j \sim i} (1 - \alpha_j) \end{aligned}$$



$$\Pr \left[ \bigwedge_{i=1}^m \overline{A_i} \right] \geq \prod_{i=1}^m (1 - \alpha_i)$$

# $k$ -SAT

- $n$  **Boolean variables**:  $x_1, x_2, \dots, x_n \in \{\text{true}, \text{false}\}$
- **conjunctive normal form**:

$$\textcolor{red}{k}\text{-CNF} \quad \phi = C_1 \wedge C_2 \wedge \dots \wedge C_m$$

“**Is  $\phi$  satisfiable?**”

- $m$  **clauses**:  $C_1, C_2, \dots, C_m$
- each clause  $C_i = \ell_{i_1} \vee \ell_{i_2} \vee \dots \vee \ell_{i_k}$   
is a disjunction of  **$k$  distinct** literals
- each **literal**:  $\ell_j \in \{x_r, \neg x_r\}$  for some  $r$
- **degree  $d$** : each clause shares variables  
with at most  **$d$**  other clauses

# LLL for $k$ -SAT

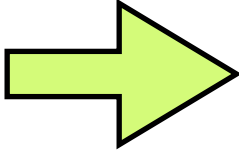
$\phi$  :  $k$ -CNF of max degree  $d$

## Theorem

$d \leq 2^{k-2}$    $\exists$  satisfying assignment for  $\phi$

uniform random assignment  $X_1, X_2, \dots, X_n$

for clause  $C_i$  , **bad event**  $A_i$  :  $C_i$  is **not** satisfied

LLL:  $e(d+1) \leq 2^k$    $\Pr \left[ \bigwedge_{i=1}^n \overline{A_i} \right] > 0$

# Algorithmic *LLL*

$\phi$  :  $k$ -CNF of max degree  $d$  with  $m$  clauses on  $n$  variables

## Theorem

$d \leq 2^{k-2}$    $\exists$  satisfying assignment for  $\phi$

## Theorem (Moser, 2009)

$d < 2^{k-3}$   satisfying assignment can be found in  $O(n + km \log m)$  w.h.p.



$\phi$  :  $k$ -CNF of max degree  $d$  with  $m$  clauses on  $n$  variables

**Solve**( $\phi$ )

pick a random assignment

$x_1, x_2, \dots, x_n;$

while  $\exists$  unsatisfied clause  $C$

**Fix**( $C$ );

**Fix**( $C$ )

replace variables in  $C$  with random values;

while  $\exists$  unsatisfied clause  $D$  overlapping with  $C$

**Fix**( $D$ );

$\phi$  :  $k$ -CNF of max degree  $d$  with  $m$  clauses on  $n$  variables

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**Fix**( $D$ );

at **top-level**:

**Observation:** A clause  $C$  is satisfied and will keep satisfied once it has been fixed.

# of **top-level** calls to **Fix**( $C$ ) :  $\leq m$  (# of clauses)

**total** # of calls to **Fix**( $C$ ) (including **recursive** calls):  $t$

$\phi$  :  $k$ -CNF of max degree  $d$  with  $m$  clauses on  $n$  variables

**Solve**( $\phi$ )

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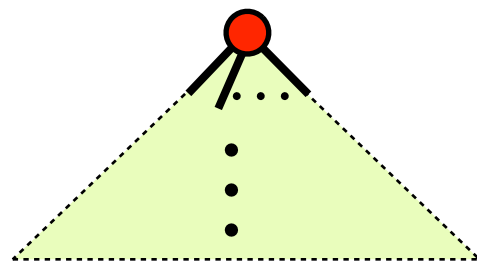
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while  $\exists$  unsatisfied clause  $D$  overlapping with  $C$

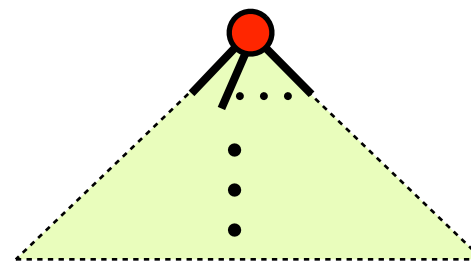
**Fix**( $D$ );

$\leq m$  recursion trees

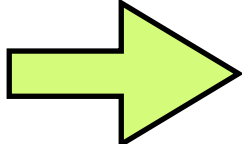
total # nodes:  $t$



...

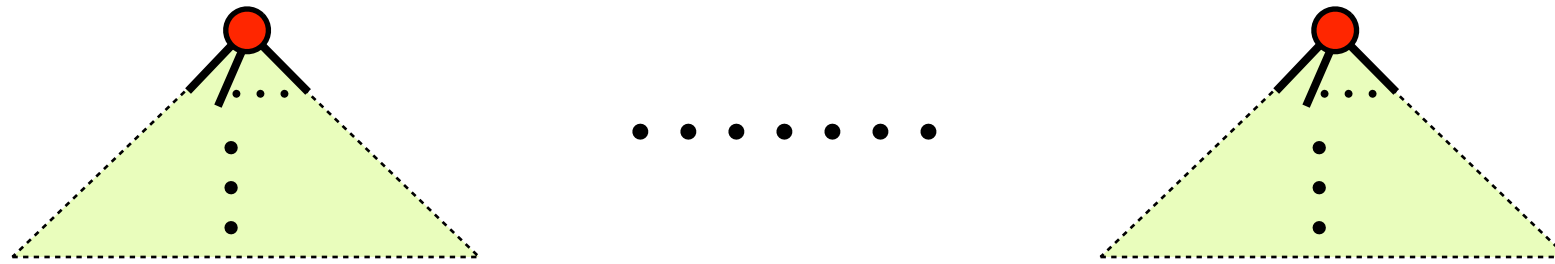


total # of random bits:  $n + tk$  (assigned bits)

**Observation:**  $\text{Fix}(C)$  is called   
assignment of  $C$  is uniquely determined

$\leq m$  recursion trees

total # nodes:  $t$



total # of random bits:  $n + tk$  (assigned bits)

the sequence of random bits is *encoded to* :

final assignment:  $n$  bits

+

recursion trees:  $\leq m \lceil \log_2 m \rceil + t(\log_2 d + 3)$  **bits**

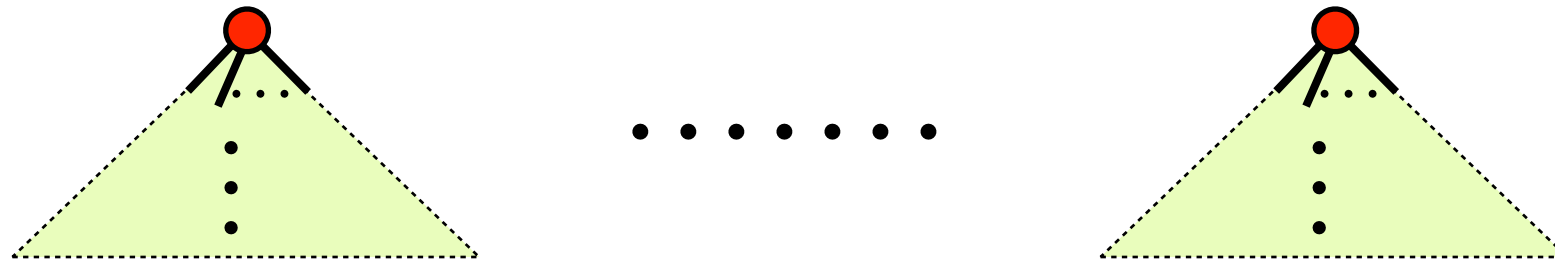
for each recursion tree:

**root:**  $\lceil \log_2 m \rceil$  **bits**

each internal **node:**  $\leq \log_2 d + \mathcal{O}(1)$  **bits**

$\leq m$  recursion trees

total # nodes:  $t$



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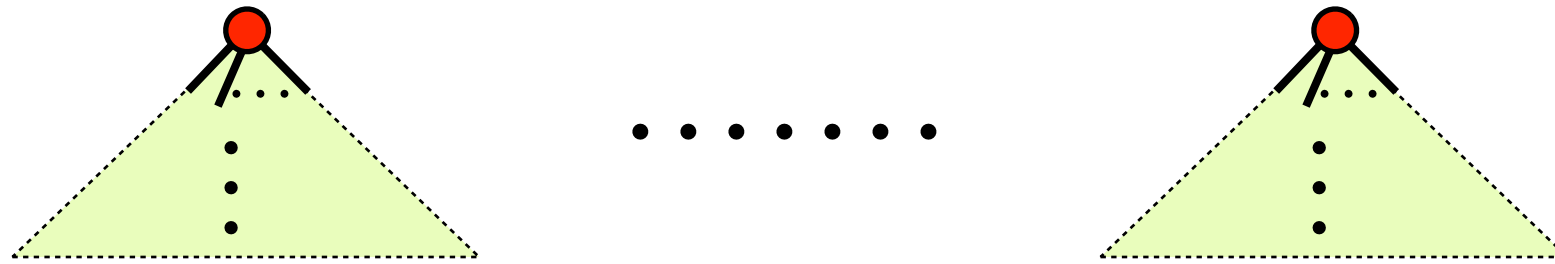
$$\leq n + m \lceil \log_2 m \rceil + t(\log_2 d + 3) \text{ bits}$$

### **Incompressibility Theorem** (Kolmogorov)

$N$  uniform random bits cannot be encoded to less than  $N - l$  bits with probability  $1 - O(2^{-l})$ .

$\leq m$  recursion trees

total # nodes:  $t$



total # of random bits:  $n + tk$  (assigned bits)

the sequence of random bits is *encoded to* :

$$\leq n + m \lceil \log_2 m \rceil + t(\log_2 d + 3) \text{ bits}$$

$$\Rightarrow t(k - 3 - \log_2 d) \leq m \lceil \log_2 m \rceil + \log n \quad \text{whp}$$

$$\text{when } d < 2^{k-3} \quad \Rightarrow \quad t \leq \frac{m \lceil \log_2 m \rceil + \log n}{k - 3 - \log_2 d}$$

total running time:  $n + tk = O(n + km \log m)$

# Algorithmic LLL

$\phi$  :  $k$ -CNF of max degree  $d$  with  $m$  clauses on  $n$  variables

$$\phi = C_1 \wedge C_2 \wedge \cdots \wedge C_m$$

**Theorem** (Moser, 2009)

$d < 2^{k-3}$   satisfying assignment can be found in  $O(n + km \log m)$  whp

**Solve**( $\phi$ )

Pick a random assignment

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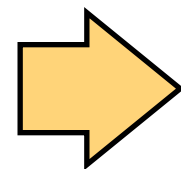
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each event is independent of all but at most  $d$  other events

### **Lovász Local Lemma (symmetric)**

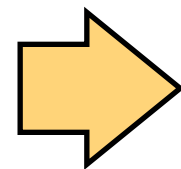
- $\forall i, \Pr[A_i] \leq p$
- $ep(d+1) \leq 1$



$$\Pr \left[ \bigwedge_{i=1}^m \overline{A_i} \right] > 0$$

### **Lovász Local Lemma (general)**

$$\begin{aligned} &\exists \alpha_1, \dots, \alpha_m \in [0, 1) \\ &\forall i, \Pr[A_i] \leq \alpha_i \prod_{j \sim i} (1 - \alpha_j) \end{aligned}$$



$$\Pr \left[ \bigwedge_{i=1}^m \overline{A_i} \right] \geq \prod_{i=1}^m (1 - \alpha_i)$$



*mutually independent* random variables:  $X \in \mathcal{X}$

*bad events*:  $A \in \mathcal{A}$  defined on variables in  $\mathcal{X}$

$\text{vbl}(A) \subseteq \mathcal{X}$ : set of variables on which  $A$  is defined

*neighborhood*:  $\Gamma(A) = \{ B \in \mathcal{A} \mid B \neq A \text{ and } \text{vbl}(A) \cap \text{vbl}(B) \neq \emptyset \}$

*inclusive neighborhood*:  $\Gamma^+(A) = \Gamma(A) \cup \{ A \}$

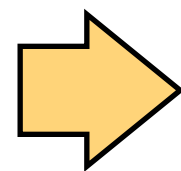
“events that are dependent with  $A$ ,  
excluding/including  $A$  itself”

### **Lovász Local Lemma (general)**

$$\exists \alpha : \mathcal{A} \rightarrow [0, 1)$$

$$\forall A \in \mathcal{A} :$$

$$\Pr[A] \leq \alpha(A) \prod_{B \in \Gamma(A)} (1 - \alpha(B))$$



$$\Pr \left[ \bigwedge_{A \in \mathcal{A}} \overline{A} \right] \geq \prod_{A \in \mathcal{A}} (1 - \alpha(A)) > 0$$

*mutually independent* random variables:  $X \in \mathcal{X}$

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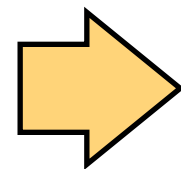
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$\exists$  values of variables in  $\mathcal{X}$   
violating all events  $A \in \mathcal{A}$   
simultaneously.

# Algorithmic LLL

*bad* events  $A \in \mathcal{A}$  defined on  
*mutually independent* random variables  $X \in \mathcal{X}$

$\text{vbl}(A)$ : set of variables on which  $A$  is defined

neighborhood  $\Gamma(A)$  and *inclusive* neighborhood  $\Gamma^+(A)$

## Assumption:

- I. We can efficiently sample an independent evaluation of every random variable  $X \in \mathcal{X}$ .
- II. We can efficiently check the violation of every event  $A \in \mathcal{A}$ .

*RandomSolver:*

sample all  $X \in \mathcal{X}$ ;

while  $\exists$  a non-violated bad event  $A \in \mathcal{A}$ :

    resample all  $X \in \text{vbl}(A)$ ;

*bad events*  $A \in \mathcal{A}$  defined on  
*mutually independent random variables*  $X \in \mathcal{X}$

$\text{vbl}(A)$ : set of variables on which  $A$  is defined

neighborhood  $\Gamma(A)$  and *inclusive* neighborhood  $\Gamma^+(A)$

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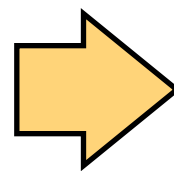
resample all  $X \in \text{vbl}(A)$ ;

**Moser-Tardos 2010:**

$\exists \alpha : \mathcal{A} \rightarrow [0, 1)$

$\forall A \in \mathcal{A} :$

$$\Pr[A] \leq \alpha(A) \prod_{B \in \Gamma(A)} (1 - \alpha(B))$$



*RandomSolver* finds values of  
all  $X \in \mathcal{X}$  violating all  $A \in \mathcal{A}$   
within expected  
resamples.

$$\sum_{A \in \mathcal{A}} \frac{\alpha(A)}{1 - \alpha(A)}$$

*bad events*  $A \in \mathcal{A}$  defined on  
*mutually independent random variables*  $X \in \mathcal{X}$

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neighborhood  $\Gamma(A)$  and *inclusive* neighborhood  $\Gamma^+(A)$

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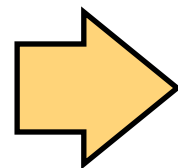
sample all  $X \in \mathcal{X}$ ;

while  $\exists$  a non-violated bad event  $A \in \mathcal{A}$ :

resample all  $X \in \text{vbl}(A)$ ;

**Moser-Tardos** 2010:

- $\forall A \in \mathcal{A}, \Pr[A] \leq p$
- $ep(d + 1) \leq 1$   
where  $d = \max_A |\Gamma(A)|$



*RandomSolver* finds values of  
all  $X \in \mathcal{X}$  violating all  $A \in \mathcal{A}$   
within expected  $|\mathcal{A}|/d$  resamples.

# $k$ -SAT

$\phi$  :  $k$ -CNF of max degree  $d$  with  $m$  clauses on  $n$  variables

*RandomSolver*:

pick a random assignment  $x_1, x_2, \dots, x_n$ ;

while  $\exists$  an unsatisfied clause  $C$ :

    replace variables in  $C$  with random values;

$$d \leq 2^{k-2} \quad \longrightarrow \quad \left( e(d+1) \leq 2^k \right)$$

*RandomSolver* returns  
a satisfying assignment within  
expected  $O(n + km/d)$  time

*bad events*  $A \in \mathcal{A}$  defined on  
*mutually independent random variables*  $X \in \mathcal{X}$

$\text{vbl}(A)$ : set of variables on which  $A$  is defined

neighborhood  $\Gamma(A)$  and *inclusive* neighborhood  $\Gamma^+(A)$

*RandomSolver*:

sample all  $X \in \mathcal{X}$ ;

while  $\exists$  a non-violated bad event  $A \in \mathcal{A}$ :

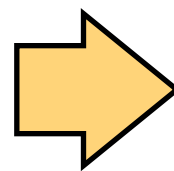
resample all  $X \in \text{vbl}(A)$ ;

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$\exists \alpha : \mathcal{A} \rightarrow [0, 1)$

$\forall A \in \mathcal{A} :$

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*RandomSolver* finds values of  
all  $X \in \mathcal{X}$  violating all  $A \in \mathcal{A}$   
within expected  
resamples.

$$\sum_{A \in \mathcal{A}} \frac{\alpha(A)}{1 - \alpha(A)}$$

*RandomSolver:*

sample all  $X \in \mathcal{X}$ ;

while  $\exists$  a non-violated  $A \in \mathcal{A}$ :

**resample** all  $X \in \text{vbl}(A)$ ;

execution log  $\Lambda$ :

$$\Lambda_1, \Lambda_2, \Lambda_3, \dots \in \mathcal{A}$$

random sequence of **resampled** events

$$N_A = |\{ i \mid \Lambda_i = A \}|$$

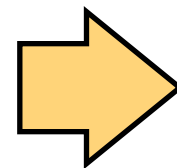
total # of times of  $A$  is resampled

**Moser-Tardos 2010:**

$$\exists \alpha : \mathcal{A} \rightarrow [0, 1)$$

$$\forall A \in \mathcal{A} :$$

$$\Pr[A] \leq \alpha(A) \prod_{B \in \Gamma(A)} (1 - \alpha(B))$$



$$\forall A \in \mathcal{A} :$$

$$\mathbb{E}[N_A] \leq \frac{\alpha(A)}{1 - \alpha(A)}$$



*RandomSolver:*

sample all  $X \in \mathcal{X}$ ;  
while  $\exists$  a non-violated  $A \in \mathcal{A}$ :  
    **resample** all  $X \in \text{vbl}(A)$ ;

**execution log**  $\Lambda$ :

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random sequence of **resampled** events

**witness tree**: A witness tree  $\tau$  is a labeled tree in which every vertex  $v$  is labeled by an event  $A_v \in \mathcal{A}$ , such that *siblings* have distinct labels.

$T(\Lambda, t)$  is a witness tree constructed from exe-log  $\Lambda$ :

- initially,  $T$  is a single root with label  $\Lambda_t$
- for  $i = t-1, t-2, \dots, 1$ 
  - if  $\exists$  a vertex  $v$  in  $T$  with label  $A_v \in \Gamma^+(\Lambda_i)$ 
    - add a new child  $u$  to the deepest such  $v$  and label it with  $\Lambda_i$
- $T(\Lambda, t)$  is the resulting  $T$

$T(\Lambda, s) \neq T(\Lambda, t)$  for  $s \neq t$

$\mathcal{T}_A$ : set of all witness trees with root-label  $A$


$$\mathbf{E}[N_A] = \sum_{\tau \in \mathcal{T}_A} \Pr[\exists t, T(\Lambda, t) = \tau]$$

*RandomSolver:*

sample all  $X \in \mathcal{X}$ ;  
while  $\exists$  a non-violated  $A \in \mathcal{A}$ :  
    **resample** all  $X \in \text{vbl}(A)$ ;

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random sequence of **resampled** events

LLL hypothesis:  $\exists \alpha : \mathcal{A} \rightarrow [0, 1)$   
 $\forall A \in \mathcal{A} : \Pr[A] \leq \alpha(A) \prod_{B \in \Gamma(A)} (1 - \alpha(B))$

total # of times of  
 $A$  is resampled

$$N_A = |\{ i \mid \Lambda_i = A \}|$$

$$\mathbf{E}[N_A] = \sum_{\tau \in \mathcal{T}_A} \Pr[\exists t, T(\Lambda, t) = \tau]$$

$$\text{(lemma 1)} \leq \sum_{\tau \in \mathcal{T}_A} \prod_{v \in \tau} \Pr[A_v]$$

$$\text{(hypothesis of LLL)} \leq \sum_{\tau \in \mathcal{T}_A} \prod_{v \in \tau} \left[ \alpha(A_v) \prod_{B \in \Gamma(A_v)} (1 - \alpha(B)) \right]$$

$$\text{(lemma 2)} \leq \frac{\alpha(A)}{1 - \alpha(A)}$$

*RandomSolver:*

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    - add a new child  $u$  to the deepest such  $v$  and label it with  $\Lambda_i$
- $T(\Lambda, t)$  is the resulting  $T$

**Lemma 1** For any particular witness tree  $\tau$ :

$$\Pr[\exists t, T(\Lambda, t) = \tau] \leq \prod_{v \in \tau} \Pr[A_v]$$

grow a random witness tree  $T_A \in \mathcal{T}_A$  :

- initially,  $T_A$  is a single root with label  $A$
- for  $i = 1, 2, \dots$ 
  - for every vertex  $v$  at depth  $i$  (root has depth 1) in  $T_A$
  - for every  $B \in \Gamma^+(A_v)$ :
    - add a new child  $u$  to  $v$  independently with probability  $\alpha(B)$ ;
    - and label it with  $B$ ;
- stop if no new child added for an entire level

**Lemma 2** For any particular witness tree  $\tau \in \mathcal{T}_A$ :

$$\Pr[T_A = \tau] = \frac{1 - \alpha(A)}{\alpha(A)} \prod_{v \in \tau} \left[ \alpha(A_v) \prod_{B \in \Gamma(A_v)} (1 - \alpha(B)) \right]$$

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 $A$  is resampled

$$N_A = |\{ i \mid \Lambda_i = A \}|$$

$$\mathbf{E}[N_A] = \sum_{\tau \in \mathcal{T}_A} \Pr[\exists t, T(\Lambda, t) = \tau]$$

$$\text{(lemma 1)} \leq \sum_{\tau \in \mathcal{T}_A} \prod_{v \in \tau} \Pr[A_v]$$

$$\text{(hypothesis of LLL)} \leq \sum_{\tau \in \mathcal{T}_A} \prod_{v \in \tau} \left[ \alpha(A_v) \prod_{B \in \Gamma(A_v)} (1 - \alpha(B)) \right]$$

$$\text{(lemma 2)} \leq \frac{\alpha(A)}{1 - \alpha(A)} \sum_{\tau \in \mathcal{T}_A} \Pr[T_A = \tau] \leq \frac{\alpha(A)}{1 - \alpha(A)}$$

*bad events*  $A \in \mathcal{A}$  defined on  
*mutually independent random variables*  $X \in \mathcal{X}$

$\text{vbl}(A)$ : set of variables on which  $A$  is defined

neighborhood  $\Gamma(A)$  and *inclusive* neighborhood  $\Gamma^+(A)$

*RandomSolver*:

sample all  $X \in \mathcal{X}$ ;

while  $\exists$  a non-violated bad event  $A \in \mathcal{A}$ :

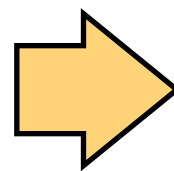
resample all  $X \in \text{vbl}(A)$ ;

**Moser-Tardos 2010:**

$\exists \alpha : \mathcal{A} \rightarrow [0, 1)$

$\forall A \in \mathcal{A} :$

$$\Pr[A] \leq \alpha(A) \prod_{B \in \Gamma(A)} (1 - \alpha(B))$$



*RandomSolver* finds values of  
all  $X \in \mathcal{X}$  violating all  $A \in \mathcal{A}$   
within expected  
resamples.

$$\sum_{A \in \mathcal{A}} \frac{\alpha(A)}{1 - \alpha(A)}$$