

Theoretical Foundations for Computational Sampling

计算采样的理论基础



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Turing's Proof (1936)



David Hilbert

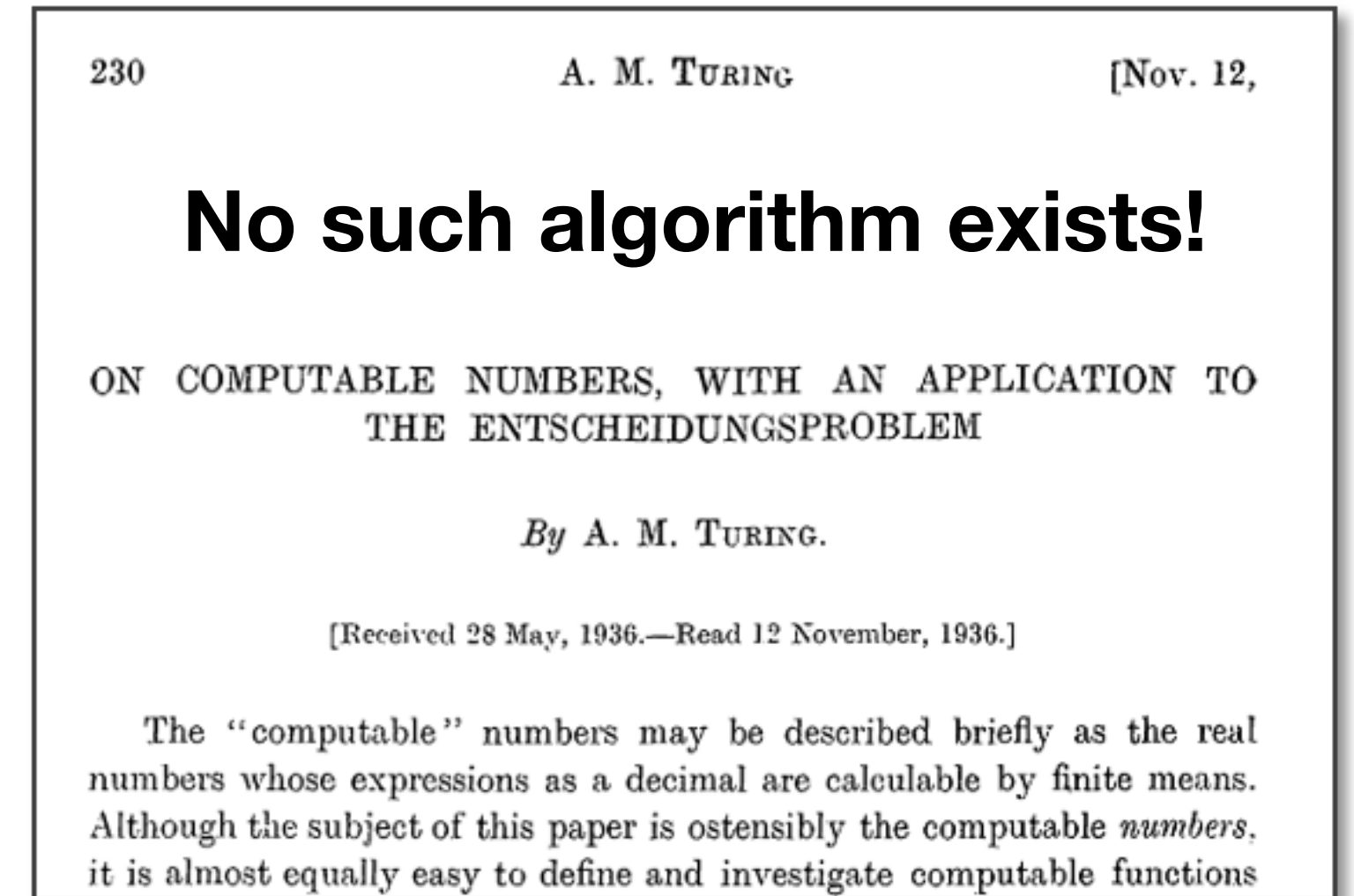
Entscheidungsproblem (1928):

Give an algorithm which determines the validity of mathematical statements.

Is Mathematics decidable?

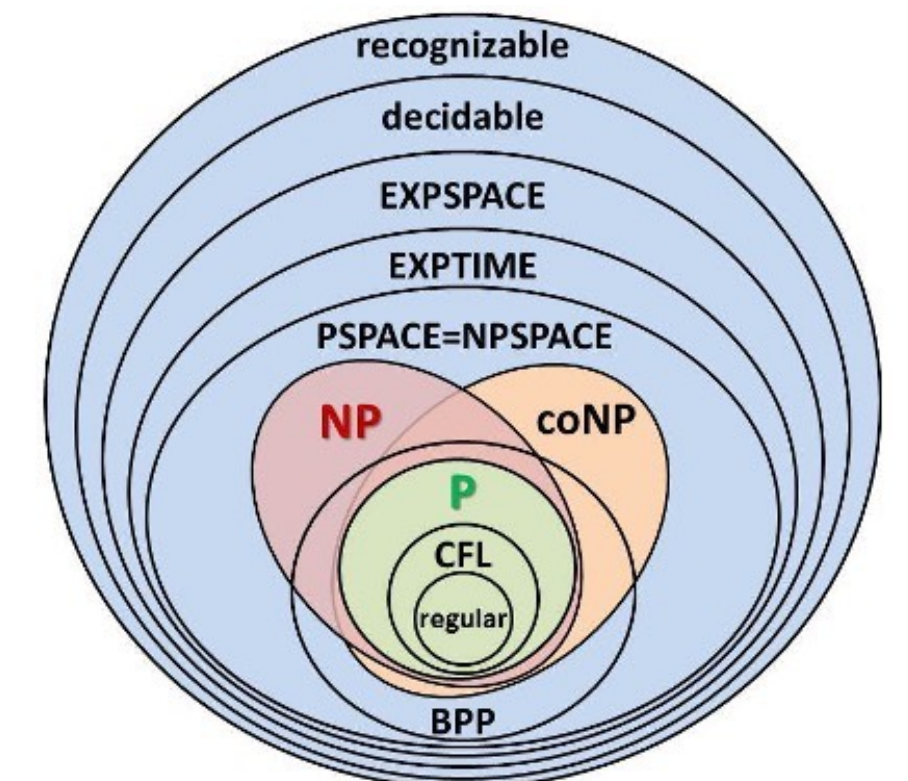


Alan Turing



The Birth of (Theoretical) Computer Science

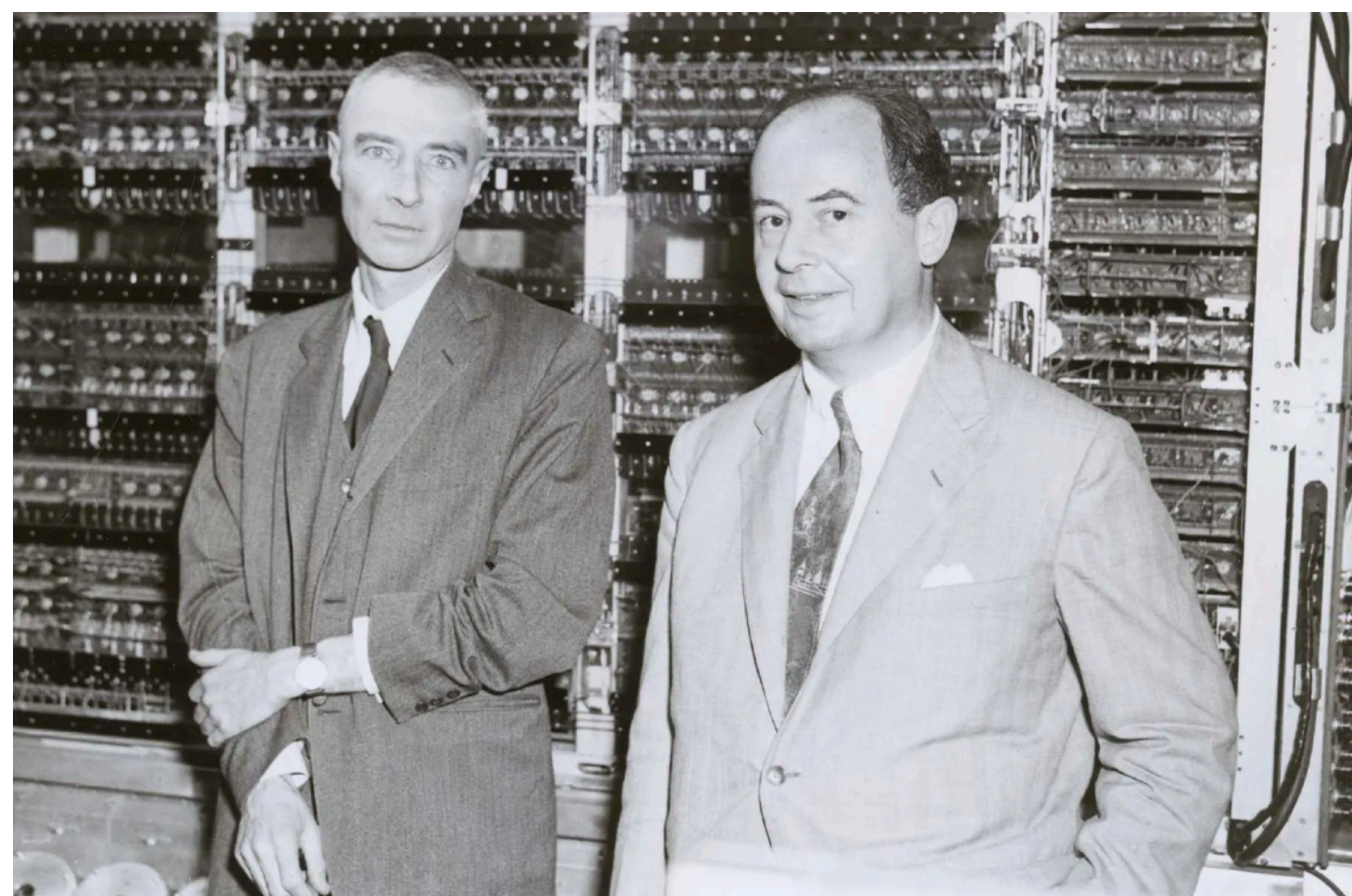
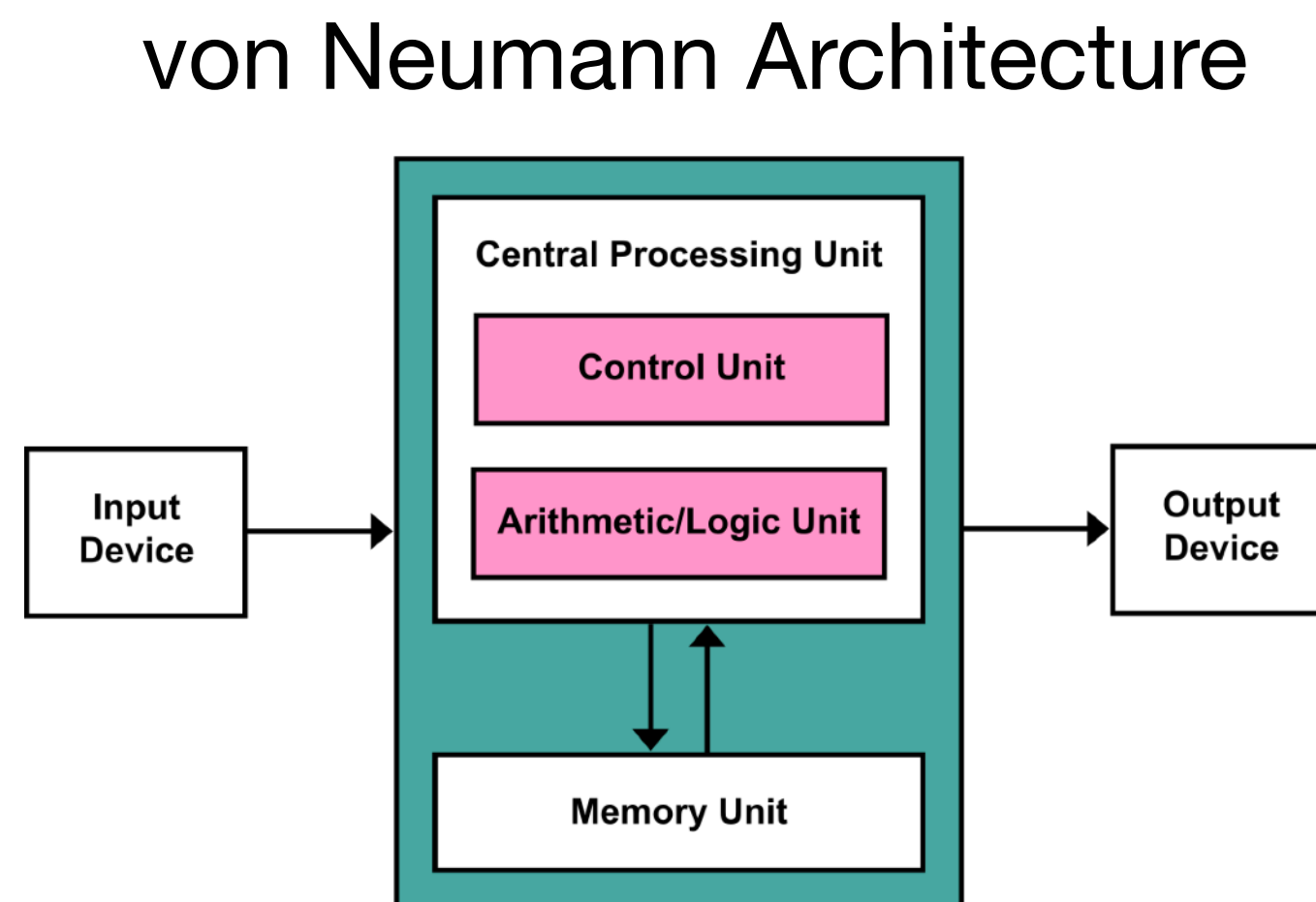
- Computation is incomplete: not all problems are computable
- “*What makes a problem easy/hard to resolve by computer?*”



Los Alamos National Lab (1945 ~ 1947)



John von Neumann

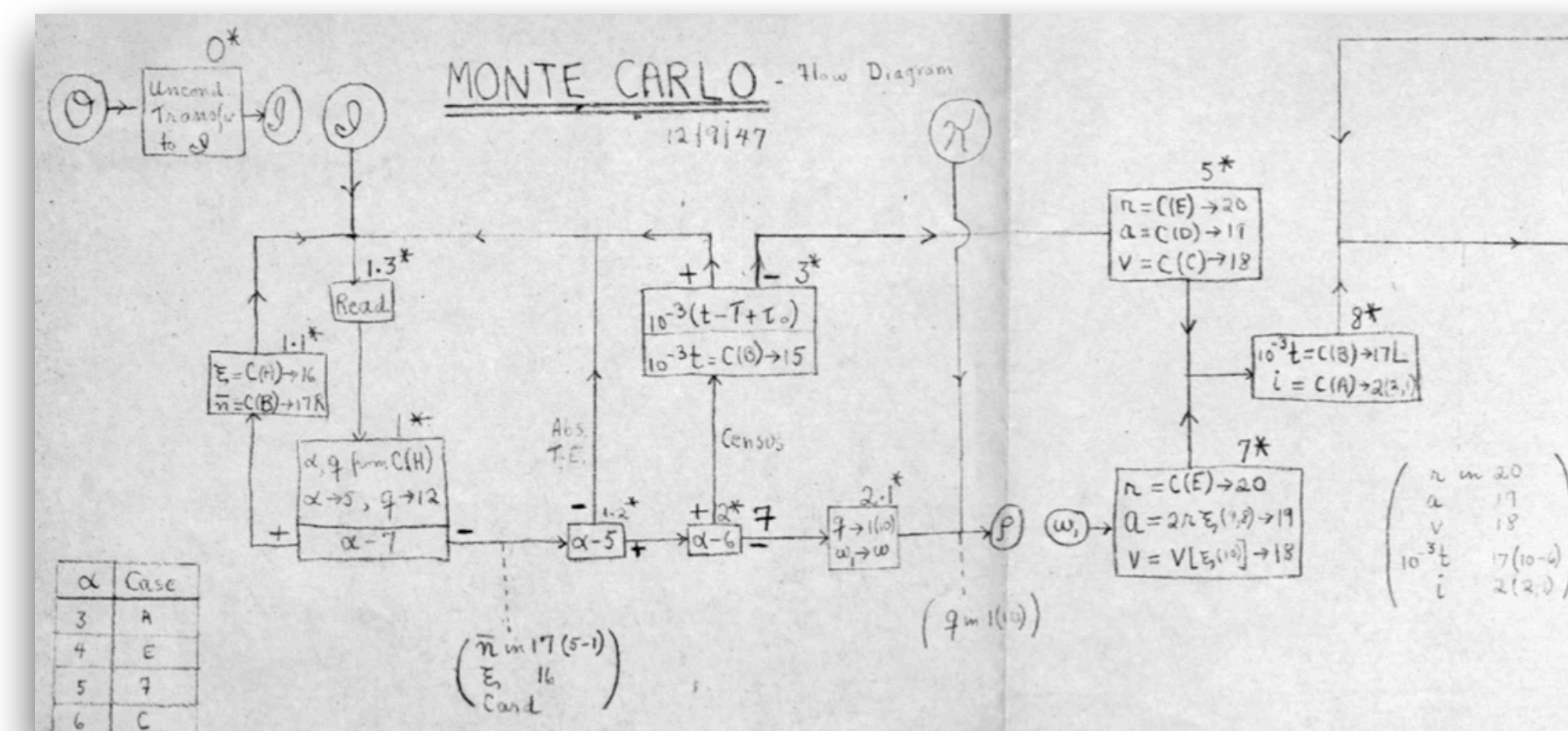
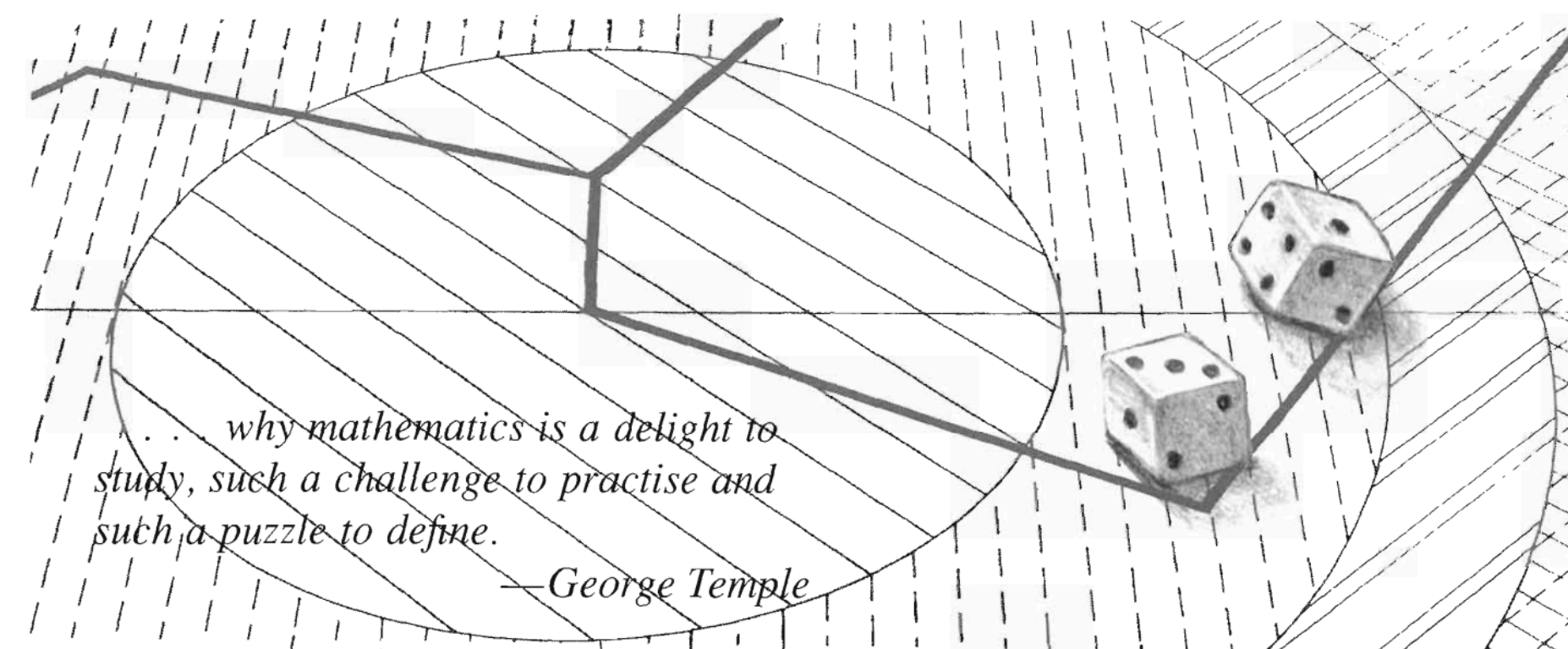


ENIAC

(Electronic Numerical Integrator and Computer)

THE BEGINNING *of the* MONTE CARLO METHOD

by N. Metropolis



Monte Carlo Method

Los Alamos National Lab (1945 ~ 1947)



John von Neumann

von Neumann Architecture

Input Device

Central Processing Unit

Control Unit

Arithmetic/Logic Unit

Memory Unit

Output Device

ENIAC
(Electronic Numerical **Integrator** and Computer)

THE BEGINNING *of the* MONTE CARLO METHOD

Codename *Monte Carlo*

Independently

Nicholas Metropolis

Stanislaw Ulam

John von Neumann

Enrico Fermi

MONTE CARLO - Flow Diagram
12/9/47

Handwritten flow diagram showing steps 0* through 8* for the Monte Carlo method, including calculations for n , a , v , i , α , β , γ , δ , ϵ , ζ , η , θ , ι , κ , λ , μ , ν , ξ , \omicron , π , ρ , σ , τ , υ , ϕ , χ , ψ , ω , δ , ϵ , ζ , η , θ , ι , κ , λ , μ , ν , ξ , \omicron , π , ρ , σ , τ , υ , ϕ , χ , ψ , ω .

Monte Carlo Method

Computational Sampling

Draw a random sample $X = (X_1, \dots, X_n)$ according to distribution μ .

- Can solve the problems [*e.g. neutron diffusion in the core of a nuclear weapon*] that were difficult to solve using conventional, deterministic methods.

- Boltzmann distribution (Gibbs measure) in statistical physics:

(locally interacting
particle states)

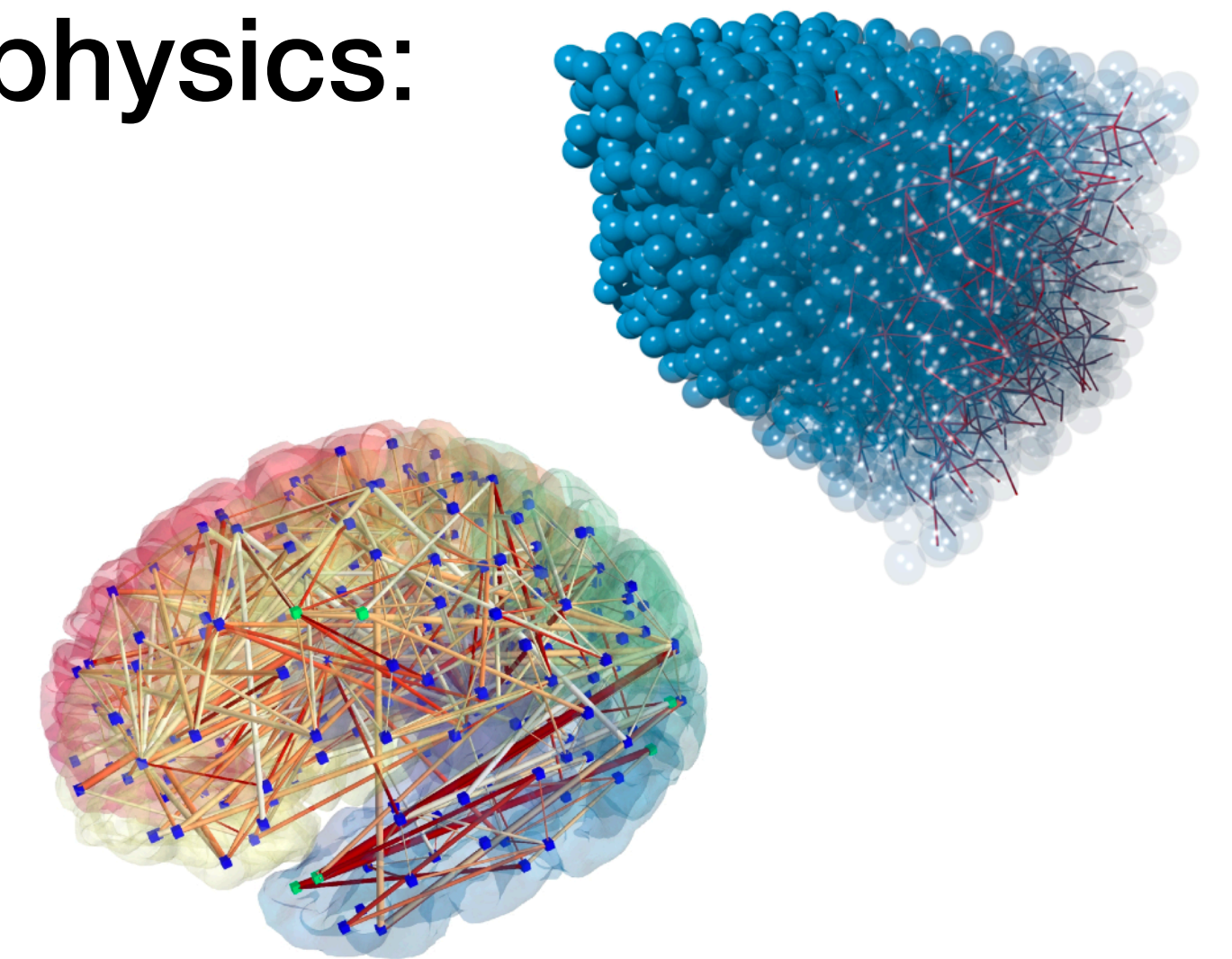
$$\mu(X) \propto \exp \left(-\beta \sum_j H_{\Lambda_j}(X_{\Lambda_j}) \right)$$

- Statistical inference/algorithms in data science:

(locally constrained
random variables)

$$\mu(X) \propto \prod_j f_j(X_{S_j})$$

- Integration in high dimension $\int_{\mathbb{R}^n}$, reliability of complex system, ...



Milestones in Theory of Computing

Draw samples $X \sim \mu \implies$ Approximate $\mu(B) = \int_B d\mu$, and many more ...

- Computational complexity of *exact computation*:
 - Leslie Valiant (1979) (Turing award 2010): #P-completeness.
 - Toda's Theorem (1991) (Gödel Prize 1998): $\text{NP}^{\text{NP}} \subseteq \text{\#P}$
 - Bulatov (2013), Dyer-Richerby (2013), Cai-Chen (2017) (Gödel Prize 2021): Complexity dichotomy.
- Monte Carlo method for *approximate computing*:
 - Dyer-Frieze-Kannan (1991) (Fulkerson Prize 1991): Integration $\int_B f(x) dx$ of convex f and volume $\text{vol}(B)$ of convex body B .
 - Jerrum-Sinclair (1989) (Gödel Prize 1996): Partition function $Z_G(\beta)$.
 - Jerrum-Sinclair-Vigoda (2004) (Fulkerson Prize 2006): Permanent $\text{perm}(A)$.

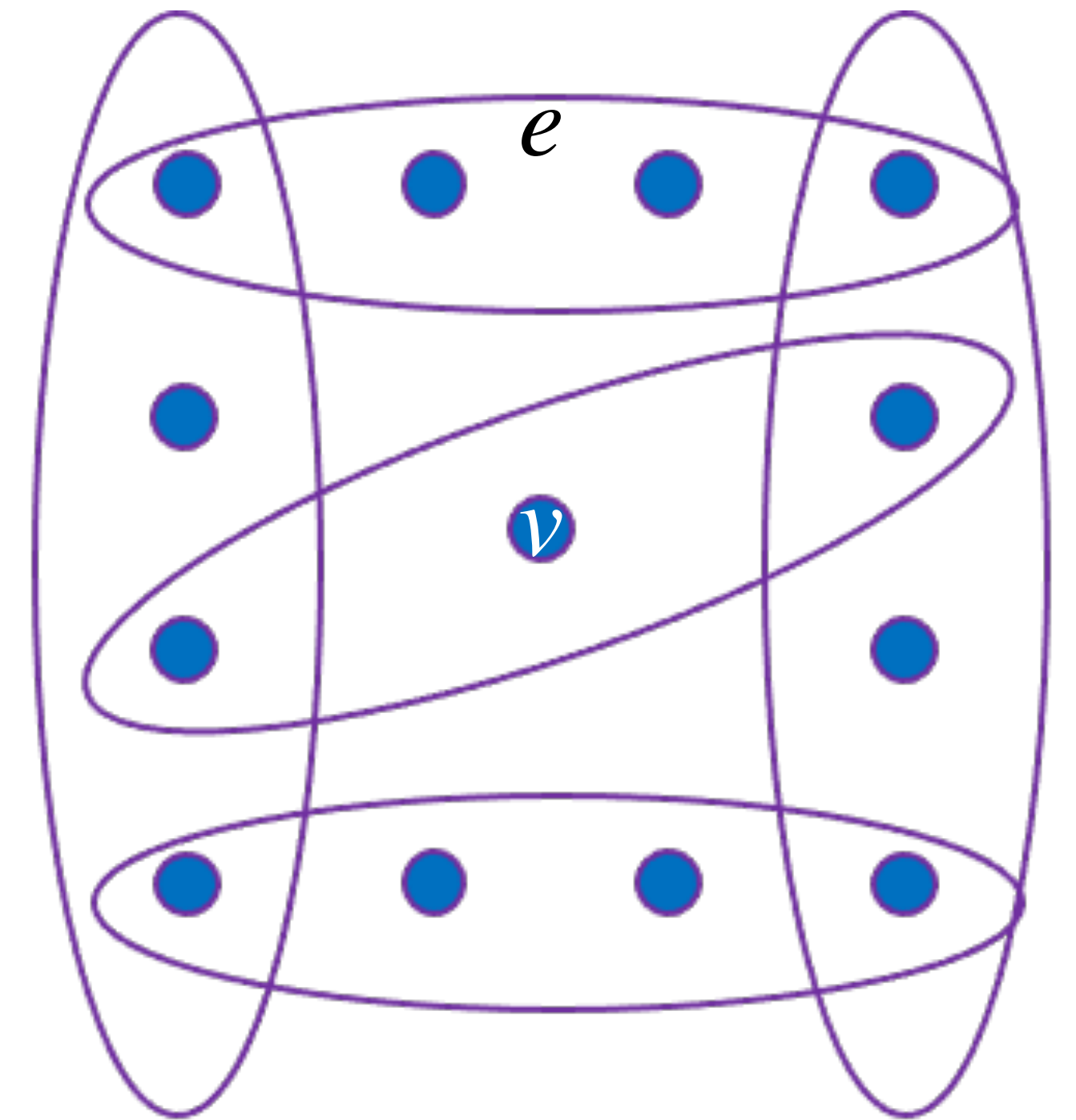
Graphical Model

(Markov random field / factor graph / weighted CSP ...)

- Hypergraph $\mathcal{H} = (V, E)$
- vertex $v \in V$ corresponds to a **variable** of domain $[q]$
- hyperedge $e \in E$ (which is a vertex subset $e \subseteq V$)
is associated with a **constraint** $f_e : [q]^e \rightarrow \mathbb{R}_{\geq 0}$
- **Gibbs distribution** μ over all configurations $\sigma \in [q]^V$:

$$\mu(\sigma) \propto \prod_{e \in E} f_e(\sigma_e)$$

• $\mu(\sigma) = \frac{\prod_{e \in E} f_e(\sigma_e)}{Z}$ where $Z := \sum_{\sigma \in [q]^V} \prod_{e \in E} f_e(\sigma_e)$ is called the **partition function**



Markov chain Monte Carlo (MCMC)

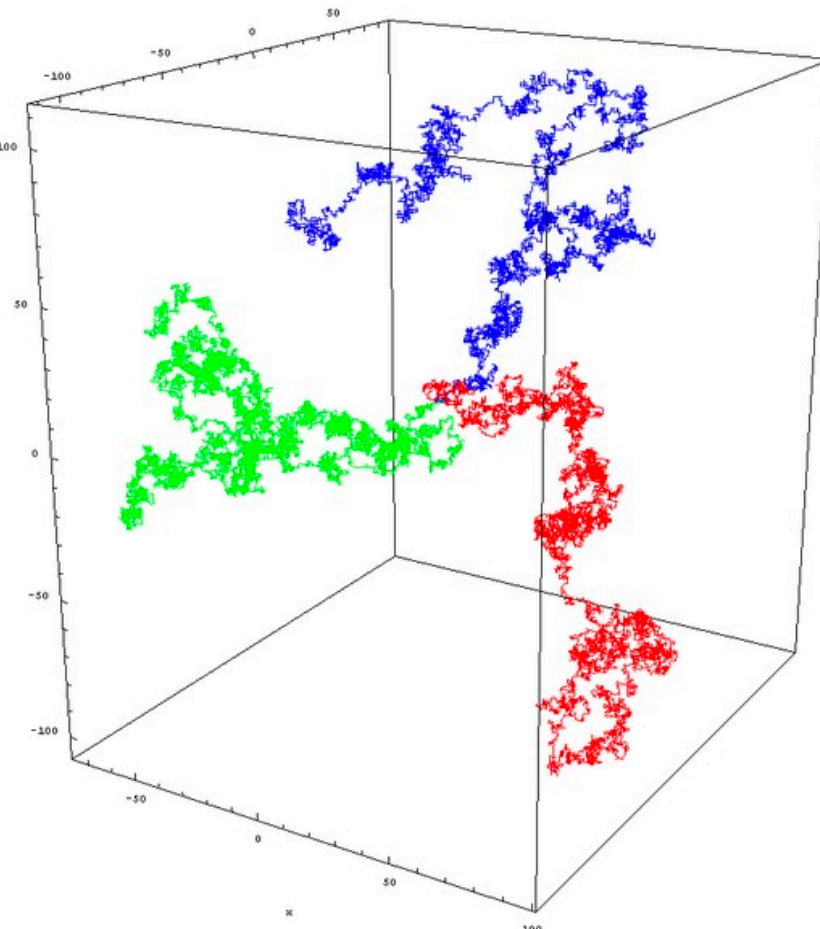
Glauber dynamics [Glauber 1963], *Gibbs sampler* [Geman-Geman 1984]

Draw a random sample $X \in [q]^V$ according to Gibbs distribution μ .

The Markov chain maintains an $X \in [q]^V$, at each step:

- pick $v \in V$ uniformly at random;
- update the evaluation of X_v according to its marginal distribution $\mu_v(\cdot \mid X_{N(v)})$.

Random walk
in configuration
space $[q]^n$



- The Markov chain has stationary distribution μ .
- **Mixing time:**
$$\tau(\epsilon) := \max_{X^{(0)} \in [q]^V} \min\{t \geq 0 \mid d_{\text{TV}}(X^{(t)}, \mu) \leq \epsilon\}$$
- **New sampling algorithms?**

Outline

- **Computational Phase Transition of Sampling**
 - Critical phenomenon for sampling *pairwise* interacting variables
 - Computational phase transition for *higher-order* interactions
(*sampling Lovász local lemma*)
- **New Paradigm for Computational Sampling**
 - Parallelism of computational sampling
 - Marginal (modular) sampling
 - Dynamic sampling

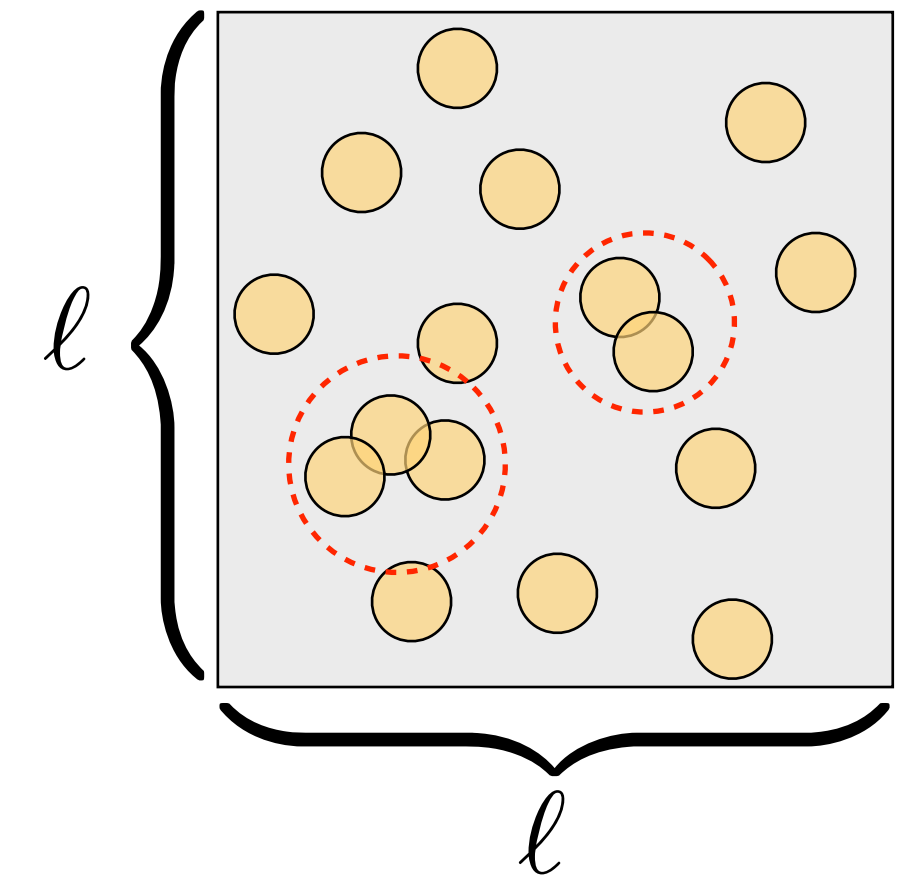
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Pennies on a Carpet

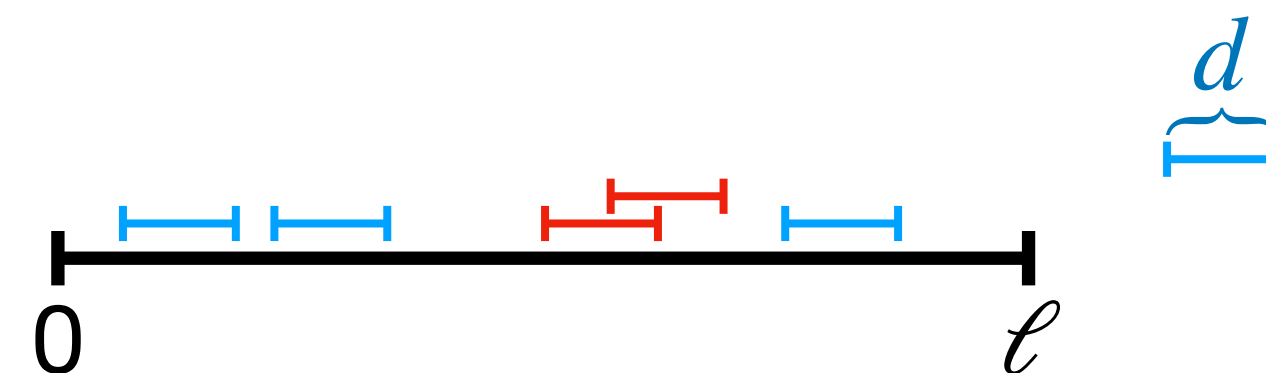
(hard spheres in 2D square)

$$n \times \text{[penny icon]} \times d$$



- Drop n pennies on a square-shape carpet at random. What is the probability that no two pennies will overlap?
- In 1-dimension (n needles on a line segment):

$$\begin{cases} \left(\frac{\ell - nd}{\ell - d} \right)^n & \text{if } \ell \geq nd \\ 0 & \text{otherwise} \end{cases}$$



- In 2-dimension: Nothing is known about this problem. as of 1979~98.

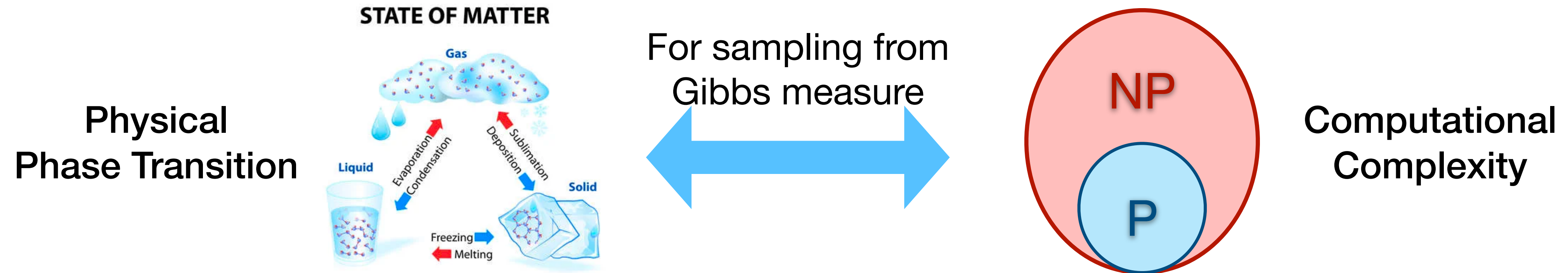
Hard spheres model: This problem is one of the most important problems of statistical mechanics. If we could answer it we would know, for example, why water boils at 100°C, on the basis of purely atomic computations.



Gian-Carlo Rota
(MIT 18.313)

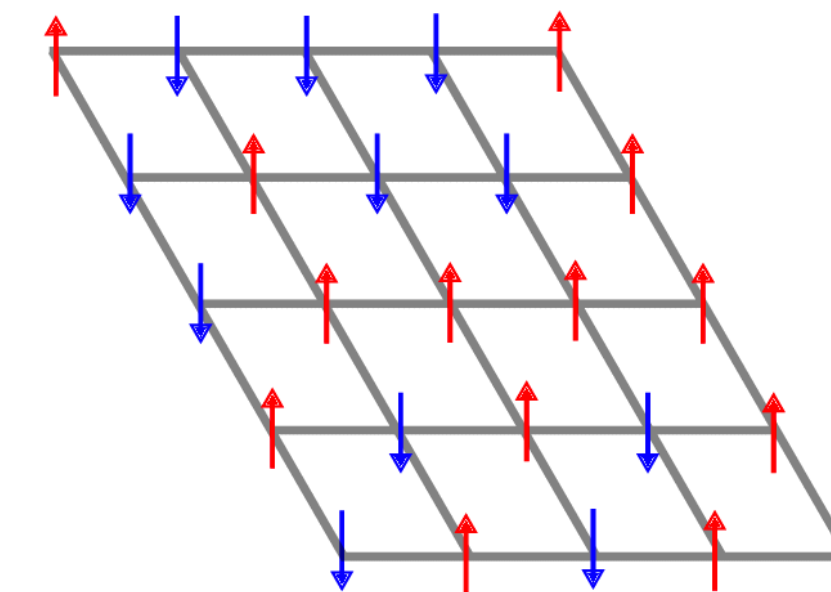
Jerrum-Guo (2021): Monte Carlo algorithm for simulating 2D hard spheres

Computational Phase Transition



- Boltzmann distribution (Gibbs measure):

$$\mu(X) \propto \prod_{(f,S) \in \mathcal{C}} f(X_S)$$



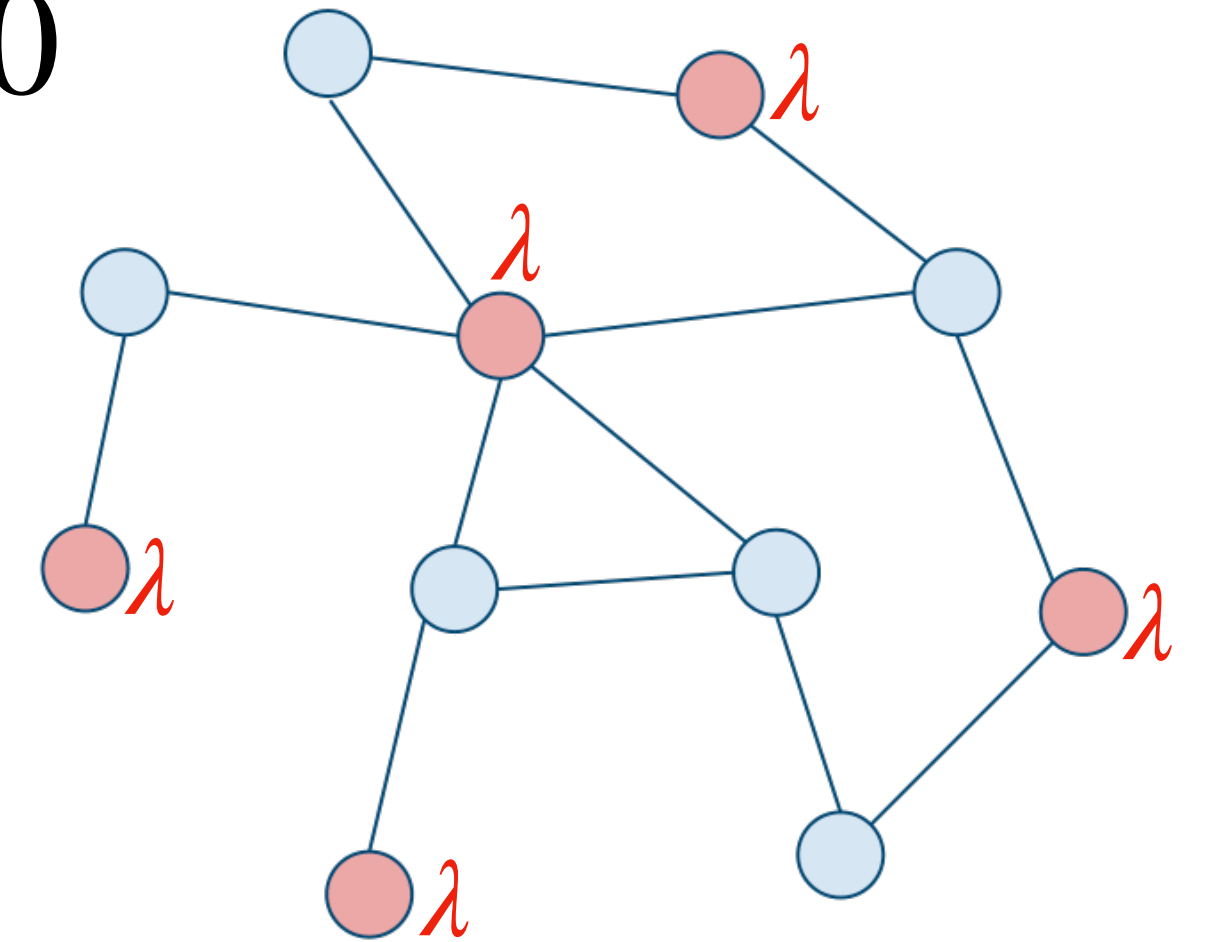
- locally constrained random variables \iff locally interacting particle states
- Continuous change of strength of local interaction \implies sharp transition of global state
(state of matter / computational complexity)

Hardcore Model (*Weighted Independent Set*)

- Sampling graph independent set with vertex weight $\lambda > 0$
(**hardcore lattice gas model** with **fugacity** $\lambda > 0$)

- In graph $G = (V, E)$ of **maximum degree** Δ :

$$\mu(I) \propto \lambda^{|I|} \text{ for independent set } I \text{ in } G$$



- **Critical threshold** (for phase transition of *uniqueness of Gibbs measure on Δ -degree Bethe lattice*):

$$\lambda_c(\Delta) \triangleq \frac{(\Delta - 1)^{\Delta-1}}{(\Delta - 2)^\Delta} \approx \frac{e}{\Delta - 2}$$

- **Computational phase transition conjecture** [Dyer-Frieze-Jerrum, FOCS '99]:

$$\text{Sampling } I \sim \mu \text{ is } \begin{cases} \mathbf{NP}\text{-hard} & \text{if } \lambda > \lambda_c(\Delta) \\ \text{poly-time} & \text{if } \lambda < \lambda_c(\Delta) \end{cases} \quad [\text{Sly, FOCS '10 best paper}]$$

Hardcore Sampler

The Markov chain:
(Gibbs sampler)

Starting from $I = \emptyset$, at each step:

- pick a uniform $v \in V$ at random;
- if $I \cup \{v\}$ is an independent set

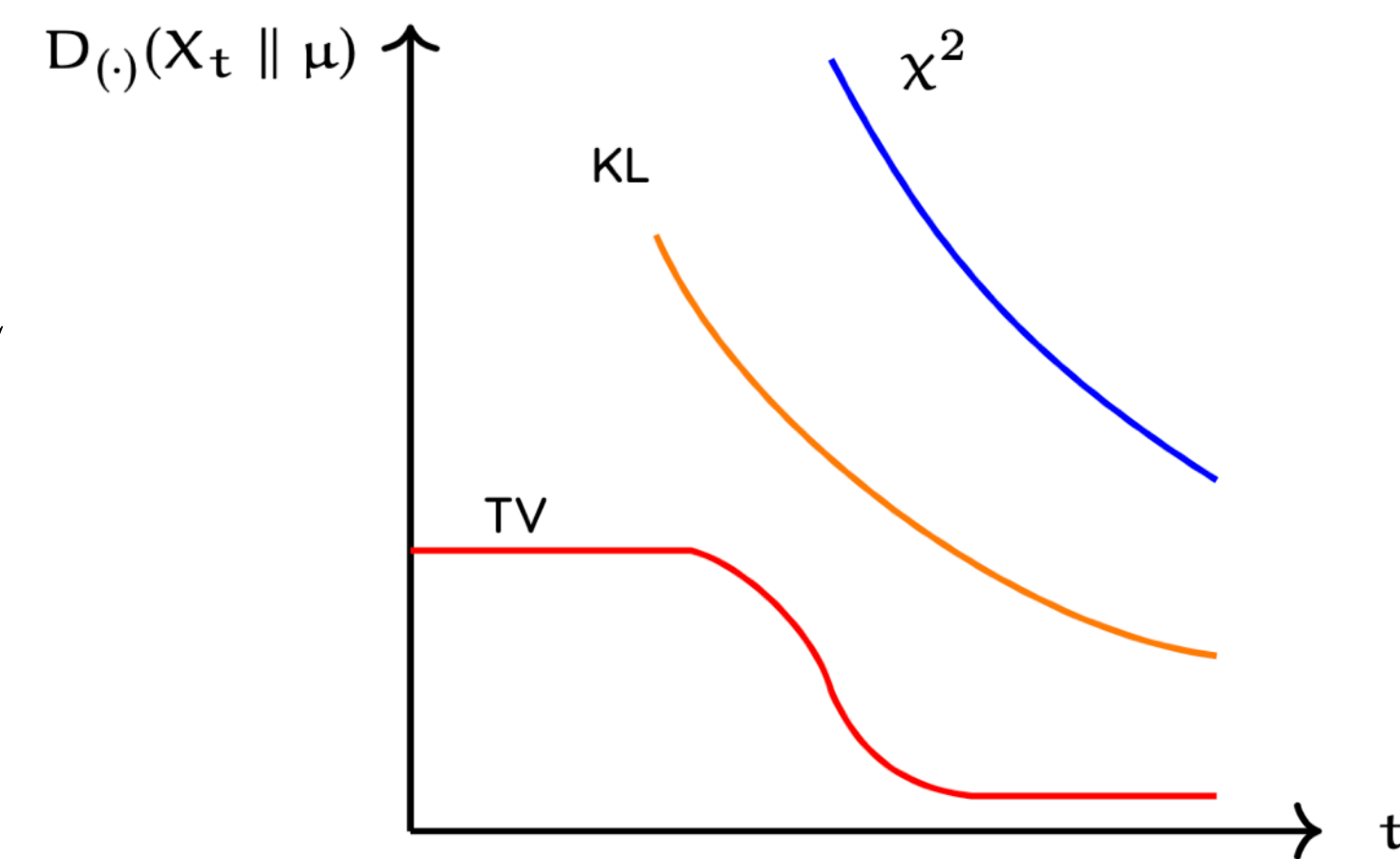
$$I \leftarrow \begin{cases} I \cup \{v\} & \text{with prob. } \frac{\lambda}{1+\lambda} \\ I \setminus \{v\} & \text{with prob. } \frac{1}{1+\lambda} \end{cases}$$

Condition	Time	
$\lambda \leq \frac{1}{\Delta-1}$	$O(n \log n)$	[Bubley-Dyer, FOCS '97]
$\lambda \leq \frac{2}{\Delta-2}$	$O(n \log n)$	[Luby-Vigoda, STOC '97]
$\lambda < \lambda_c(\Delta)$ non-Monte-Carlo	$n^{O(\log \Delta)}$	[Weitz, STOC '06]
$\lambda < \lambda_c(\Delta)$ girth ≥ 7 , large Δ	$O(n \log n)$	[Efthymiou-Hayes-Štefankovič-Vigoda-Y., FOCS '16]
$\lambda \leq (1-\delta)\lambda_c(\Delta)$	$n^{\exp(O(1/\delta))}$	[Anari-Liu-Oveis Gharan, FOCS '20]
$\lambda \leq (1-\delta)\lambda_c(\Delta)$	$n^{O(1/\delta)}$	[Chen-Liu-Vigoda, FOCS '20]
$\lambda < \lambda_c(\Delta)$	$\Delta^{O(\Delta^2)} n \log n$	[Chen-Liu-Vigoda, STOC '21]
$\lambda < \lambda_c(\Delta)$	$O(n^2 \log n)$	[Chen-Feng-Y.-Zhang, FOCS '21]
$\lambda < \lambda_c(\Delta)$ <i>balanced</i> random walk	$O(n \log n)$	[Anari-Jain-Koehler-Pham-Vuong, STOC '22]
$\lambda < \lambda_c(\Delta)$	$O(n \log n)$	[Chen-Eldan, FOCS '22]
$\lambda < \lambda_c(\Delta)$	$O(n \log n)$	[Chen-Feng-Y.-Zhang, FOCS '22]

Ind.
work {

strong spatial mixing (SSM)
spectral independence
entropic independence
high-dimensional expander (HDX)
local-to-global argument
modified log-Sobolev inequality
field dynamics
... ..

$$D_f := \mathbb{E}_{\sigma \sim \mu} \left[f \left(\frac{\nu(\sigma)}{\mu(\sigma)} \right) \right] \quad \begin{array}{l} D_{\chi^2} : f(x) = (x - 1)^2 \\ D_{\text{KL}} : f(x) = x \log x \end{array}$$



- **Poincaré inequality:** for Poincaré constant $\kappa_{\text{Poin}} < 1$

$$D_{\chi^2}(X^{(t)} \parallel \mu) \leq \kappa_{\text{Poin}} \cdot D_{\chi^2}(X^{(t-1)} \parallel \mu) \implies \tau_{\text{mix}} = O(n^2 \log n)$$

- **Modified log-Sobolev (MLS) inequality:** for MLS constant $\kappa_{\text{MLS}} < 1$

$$D_{\text{KL}}(X^{(t)} \parallel \mu) \leq \kappa_{\text{MLS}} \cdot D_{\text{KL}}(X^{(t-1)} \parallel \mu) \implies \tau_{\text{mix}} = O(n \log n)$$

- [\[Erbar-Henderson-Menz-Tetali '16\]](#) proved a *subcritical* MLS inequality via Ricci curvature
- [\[Weitz '06\]](#) proved a decay of correlation property up to critical threshold, which was used in [\[Anari-Liu-Oveis Gharan '20\]](#) [\[Chen-Liu-Vigoda '20\]](#) to imply the mixing of Glauber dynamics by a local-to-global argument in high dimension expanders, which was further refined in [\[Chen-Liu-Vigoda '21\]](#) to prove the fast mixing of $\Theta(n)$ -block dynamics
- [\[Chen-Feng-Y.-Zhang '21, '22\]](#) invented the field dynamics, which used the mixing of block dynamics to lift the subcritical MLS inequality in [\[EHMT '16\]](#) to the critical threshold

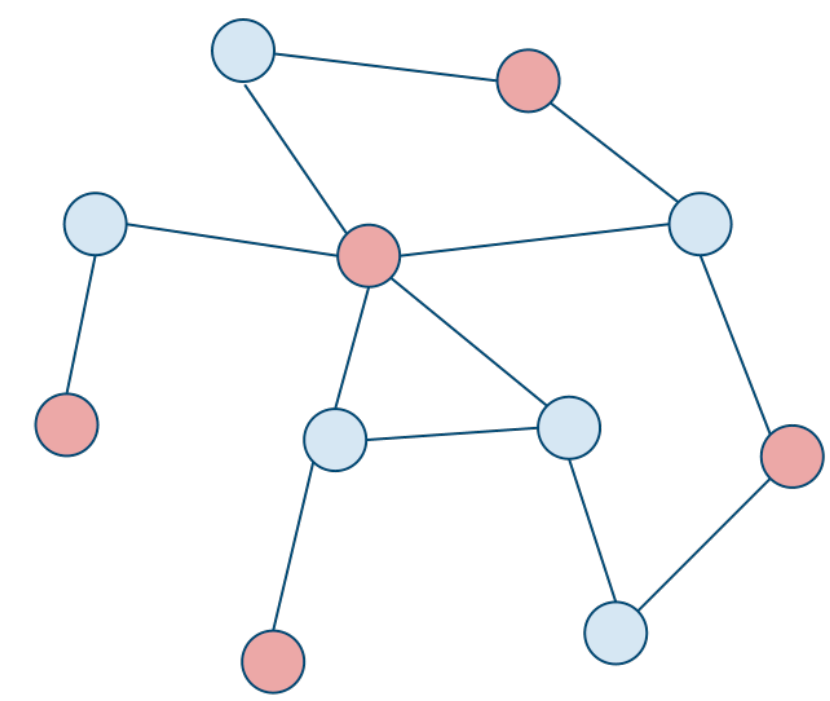
Local-to-Global Argument

Random Walk Algorithm: (Glauber Dynamics)

Starting from $I = \emptyset$, at each step:

- pick a uniform $v \in V$ at random;
- if $I \cup \{v\}$ is an independent set

$$I \leftarrow \begin{cases} I \cup \{v\} & \text{with prob. } \frac{\lambda}{1+\lambda} \\ I \setminus \{v\} & \text{with prob. } \frac{1}{1+\lambda} \end{cases}$$



- The transition matrix P for the random walk has size $\exp(\Omega(n)) \times \exp(\Omega(n))$

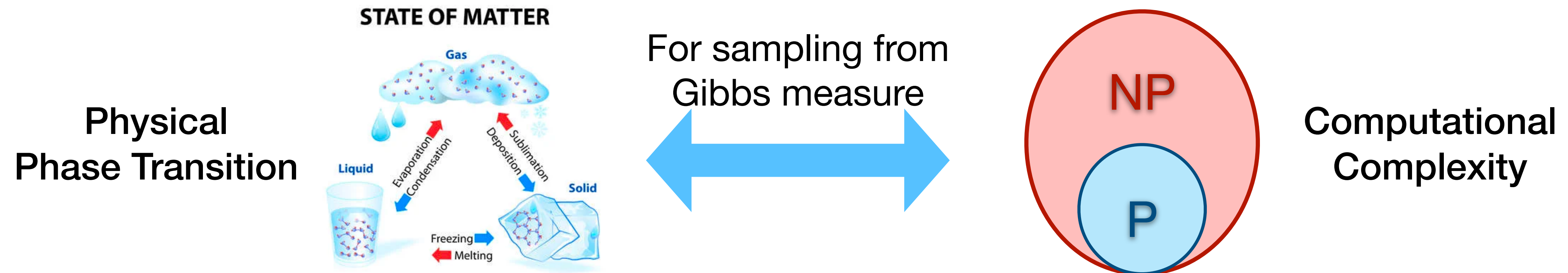
- The correlation matrix $\text{Corr}(i, j) \triangleq \frac{\text{cov}(X_i, X_j)}{\sqrt{\text{Var}(X_i)\text{Var}(X_j)}}$ for μ has size $n \times n$

- We prove (essentially) [\[Chen-Feng-Y.-Zhang, FOCS '21 FOCS '22\]](#):

$$\|\text{Corr}\| = O(1) \implies 1 - \kappa_{\{\text{Poin,MLS}\}}(P_\lambda) \geq \Omega \left(1 - \kappa_{\{\text{Poin,MLS}\}}(P_{\lambda/100}) \right)$$

- When $\lambda < \lambda_c(\Delta)$, there is decay of correlation, then $\|\text{Corr}\| = O(1)$, and therefore the Poincare/MLS constant for subcritical case $\lambda/100$ can be lifted to the near critical regime with constant overhead

Computational Phase Transition



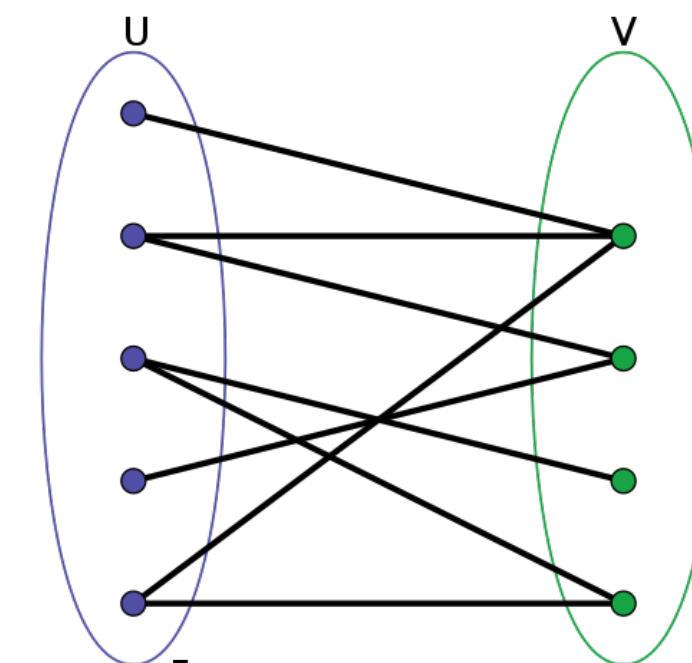
- [Chen-Feng-Y.-Zhang, FOCS '21, '22]:

For pairwise *negatively* constrained Boolean variables $X = (X_1, \dots, X_n) \sim \mu$:
(*anti-ferromagnetic Ising model / anti-ferromagnetic two-state spin systems*)

Sampling $X \sim \mu$ is $\begin{cases} \text{poly-time} & \text{within physical phase-transition cond.} \\ \mathbf{NP}\text{-hard} & \text{beyond physical phase-transition cond.} \end{cases}$

- [Jerrum-Sinclair, '92] (Gödel Prize 1996): Sampling pairwise *positively* constrained Boolean variables (*ferromagnetic Ising model*) in poly-time

Bipartite Hardcore Model (#BIS)



- Sampling independent set with vertex weight $\lambda > 0$ in a bipartite graph.
- In bipartite graph $G = (U, V, E)$:

$$\mu(I) \propto \lambda^{|I|} \text{ for independent set } I \text{ in } G$$

- **#BIS** (bipartite independent set): sampling independent set in bipartite graph
 - Many sampling/approximate counting problems are #BIS-equivalent: subclasses of #CSP, ferromagnetic spin systems, stable matchings, ...
 - The computational complexity of #BIS is still unknown.
- **[Chen-Liu-Y., FOCS '23]**: For bipartite hardcore model with **one-side** maximum degree Δ , sampling is poly-time tractable if $\lambda < \lambda_c(\Delta) = \frac{(\Delta - 1)^{\Delta-1}}{(\Delta - 2)^\Delta}$

Higher-Order (k -wise) Interactions

- For k -wise interactions, consider **hard constraints** $f : [q]^e \rightarrow \{0,1\}$

$$\mu(\sigma) \propto \prod_{e \in E} f_e(\sigma_e)$$

μ is the uniform distribution over all **constraint satisfaction solutions**

- **Example:** k -CNF (conjunctive normal form)

$$\Phi = (x_1 \vee \neg x_2 \vee x_3) \wedge (x_1 \vee x_2 \vee x_4) \wedge (x_3 \vee \neg x_4 \vee \neg x_5)$$

- **SAT** (Boolean satisfiability): determine whether there is a satisfying solution
 - **NP-complete** (Cook–Levin theorem)
 - Sample from μ (**SAT sampler**) \implies **SAT solver**

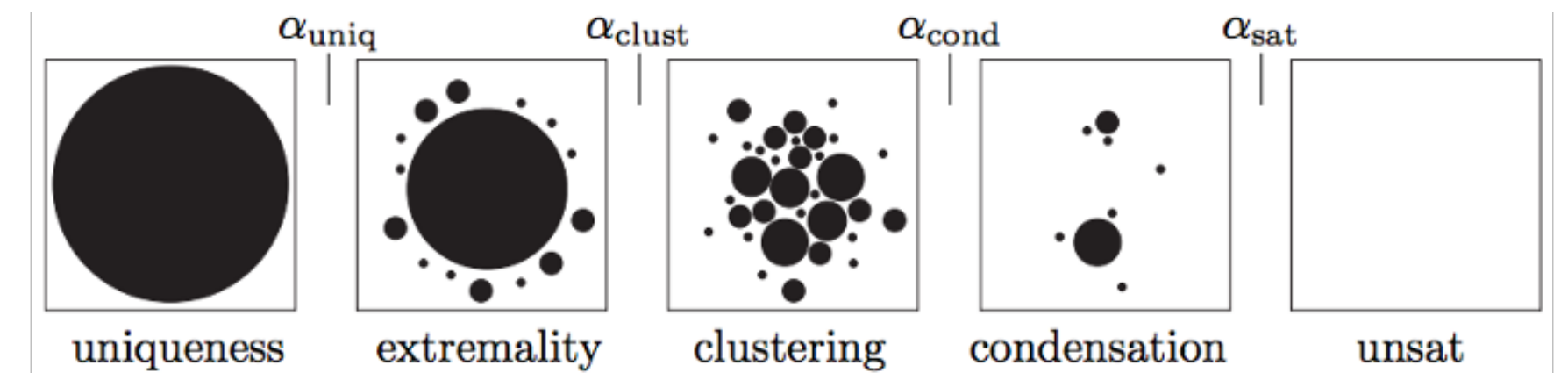
Solving vs Sampling

- For Constraint Satisfaction Problem (CSP):

$$\mu(\sigma) \propto \prod_{e \in E} f_e(\sigma_e)$$

- Lovász local lemma (1975): $pD \lesssim 1 \implies$ a SAT solution exists
 - $p = \max_e \Pr_{X \sim [q]^e} [f_e(X) = 0]$: max *violation probability* of any constraint
 - $D = \max_e |\{e' : e \cap e' \neq \emptyset\}|$: max *dependency degree* of any constraint

- Connectivity of solution space:
 - The solution space can be highly disconnected



- **Barrier:** MCMC sampling crucially relies on *connectivity* of solution space

Overcome the Connectivity Barrier

Projected Markov chain:

Properly construct a subspace $U \subseteq V$;

Sample $X_U \sim \mu_U$ by **simulating** Gibbs sampler on μ_U ;

Recover from X_U a satisfying solution $X \sim \mu$;



Idea: project onto lower dimension to improve connectivity

- **Fast sampler in near-linear time** (under *Lovász local lemma like conditions* $pD^{O(1)} \lesssim 1$):
 - SAT [Feng-Guo-Y.-Zhang, STOC 2020, JACM 2021] projected MCMC
 - CSP with *atomic* constraints [Feng-He-Y., STOC 2021] “compressed” MCMC
 - *general* CSP (*constraint satisfaction problem*) [He-Wang-Y., FOCS 2022] **new algorithm**
- “**Sampling Lovász local lemma**” conjecture: “*sampling is twice-local*”
$$pD^2 \lesssim 1 \implies \text{sampling uniform satisfying solution is poly-time}$$
- **state-of-the-arts:** $pD^5 \lesssim 1$ “5-fold local lemma” [He-Wang-Y., FOCS 2022, SODA 2023]

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Markov chain Monte Carlo (MCMC)

Gibbs sampler [\[Geman-Geman 1984\]](#) for sampling X from Gibbs distribution μ :

The Markov chain maintains an $X \in [q]^V$, at each step:

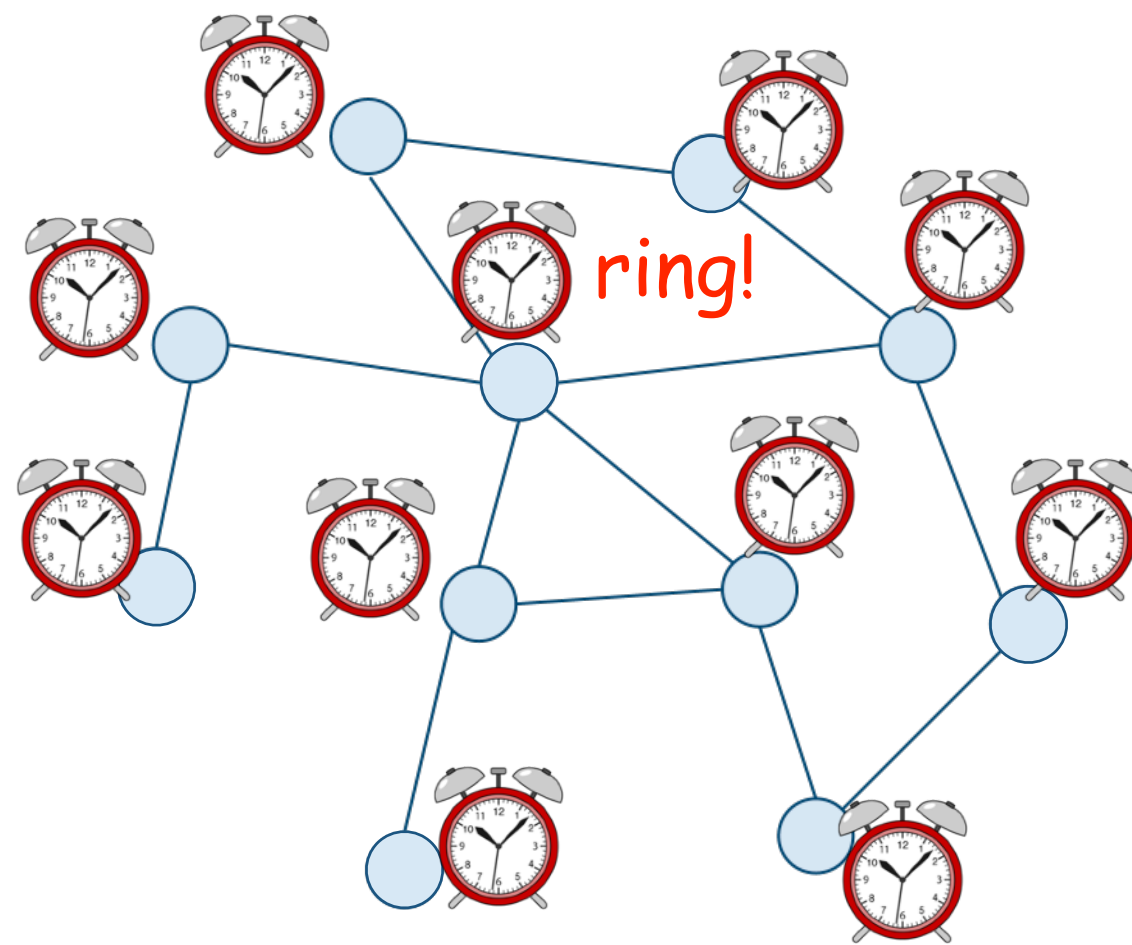
- pick $v \in V$ uniformly at random;
 - update the evaluation of X_v according to its marginal distribution $\mu_v(\cdot \mid X_{N(v)})$.
-
- Sequential algorithm that updates a single-site at each step.
 - Generic lower bound [\[Hayes-Sinclair '13\]](#):
 - any single-site dynamics requires at least $\Omega(n \log n)$ steps to converge

Idealized Parallel Process

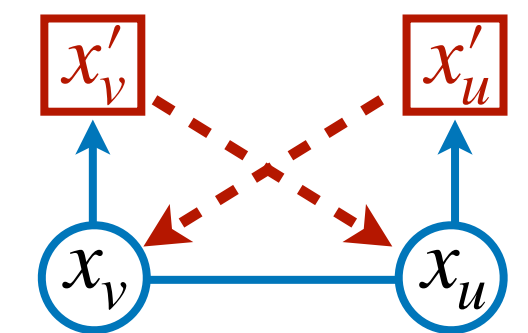
Glauber dynamics [Glauber 1963] for sampling X from Gibbs distribution μ :

The Markov chain for $X \in [q]^V$ runs in **continuous time**:

- Each $v \in V$ holds a rate-1 Poisson clock;
- upon v 's clock rings: its state X_v is updated **atomically** according to $\mu_v(\cdot \mid X_{N(v)})$.



- Idealized (*continuity* and *atomicity*) parallel process for the evolution of real physical world
- **Barrier for concurrency**: updates of adjacent sites
 - **$O(\Delta)$ overhead!**
- Fully & correctly parallelize MCMC?



Parallelism of MCMC Sampling

(Fundamental challenge in Theory of Parallel Computing)

- In a seminal paper for parallel computing [\[Mulmuley-Vazirani-Vazirani, STOC '87\]](#):
 - *“It is possible to sample uniform perfect matching in NC (poly-log rounds)?”*
 - *“It is possible to estimate permanent in NC (parallel counterpart for P)?”*
- Later, [\[Shang-Hua Teng, 1992\]](#)
 - **Proved:** classical MCMC sampling could not be efficiently parallelized
“via standard approaches of parallelization”
 - **Conjectured:** permanent estimation cannot be done in poly-log rounds
(perhaps the only problem not known to be P-complete but conjectured intrinsically sequential)

Fully Parallelize MCMC Sampling

Continuous-time Glauber dynamics (1963):

Each $v \in V$ holds a Poisson clock;

upon v 's clock rings:

- X_v is updated according to $\mu_v(\cdot \mid x_{N(v)})$;

Algorithm 1: An iterative algorithm for simulating single-site dynamics

Input: initial configuration $X_0 \in Q^V$; update schedule $\mathfrak{T} = (t_i^v)_{v \in V, 0 \leq i \leq m_v}$; assignment $\mathfrak{R} = (\mathcal{R}_{(v,i)})_{v \in V, 1 \leq i \leq m_v}$ of random bits for resolving updates.

```

1 initialize  $\ell \leftarrow 0$  and  $\hat{X}_v^{(0)}[i] \leftarrow X_0(v)$  for all  $v \in V, 0 \leq i \leq m_v$ ;
2 repeat
3    $\ell \leftarrow \ell + 1$ ;
4   forall  $v \in V$  in parallel do  $\hat{X}_v^{(\ell)}[0] \leftarrow X_0(v)$ ;
5   forall updates  $(v, i)$ , where  $v \in V, 1 \leq i \leq m_v$ , in parallel do
6     let  $\tau \in Q^{N_v^+}$  be constructed as:
7        $\forall u \in N_v^+, \tau_u \leftarrow \hat{X}_u^{(\ell-1)}[j_u]$  for  $j_u = \max\{j \geq 0 \mid t_j^u < t_i^v\}$ ;
8      $\hat{X}_v^{(\ell)}[i] \leftarrow \text{Sample}(\tau, \mathcal{R}_{(v,i)})$ ;
9   end
10 until  $\hat{X}^{(\ell)} = \hat{X}^{(\ell-1)}$ ;
```

- Suppose that all random choices have been generated:
 - time t_i^v and a *random seed* $R_{(v,i)} \in [0,1]$ for the i th update at $v \in V$
- Dynamical system for the Markov chain:

$$X_t(v) \leftarrow \text{Sample} \left(\mu_v^\tau, R_{(v,i)} \right)$$

where $\tau \in [q]^{N(v)}$ satisfies $\forall u \in N(v), \tau_u = X_{t_j^u}(u)$ for $t_j^u = \max\{t_{j'}^u : t_{j'}^u < t_i^v\}$

Fully Parallelize MCMC Sampling

Continuous-time Glauber dynamics (1963):

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5   forall updates  $(v, i)$ , where  $v \in V, 1 \leq i \leq m_v$ , in parallel do  
6     let  $\tau \in Q^{N_v^+}$  be constructed as:  
        $\forall u \in N_v^+, \tau_u \leftarrow \hat{X}_u^{(\ell-1)}[j_u]$  for  $j_u = \max\{j \geq 0 \mid t_j^u < t_i^v\}$ ;  
7      $\hat{X}_v^{(\ell)}[i] \leftarrow \text{Sample}\left(P_v^\tau, \mathcal{R}_{(v,i)}\right)$ ;  
8   end  
9 until  $\hat{X}^{(\ell)} = \hat{X}^{(\ell-1)}$ ;
```

- Key ideas:
 - Construct a **dynamical system** whose **fixpoint** corresponds to the correct evolution of the chain.
 - Simulate this dynamical system by a **locally-iterative message-passing parallel algorithm**.
 - A **universal coupling** of randomness to ensure fast **stabilization** to the correct fixpoint.
- Faithful parallel simulation of MCMC with no overhead [Liu-Y., STOC 2022]
(when the Dobrushin's influence matrix is $O(1)$ -normed)

Local Evaluating Random Vector

- Evaluate a few X_v 's in $X \in [q]^V$ drawn from a Gibbs distribution μ
(statistical inference / estimation in selected dimensions)
- **Classic MCMC:** have to compute everything even just interested in 1 variable, because all variables may be correlated
- **Marginal (modular) sampling:** with some local computational cost
evaluate X_v in $X \in [q]^V$ drawn from a Gibbs distribution μ



Classic MCMC: *Forward Simulation*

- MCMC since 1940s: simulate a dynamical system till it converges to a fixpoint
arbitrary initial state $X^{(0)}$ $\xrightarrow{\text{long enough evolution}}$ $X^* \sim \mu$ (fixpoint)

The Markov chain maintains an $X \in [q]^V$, at each step:

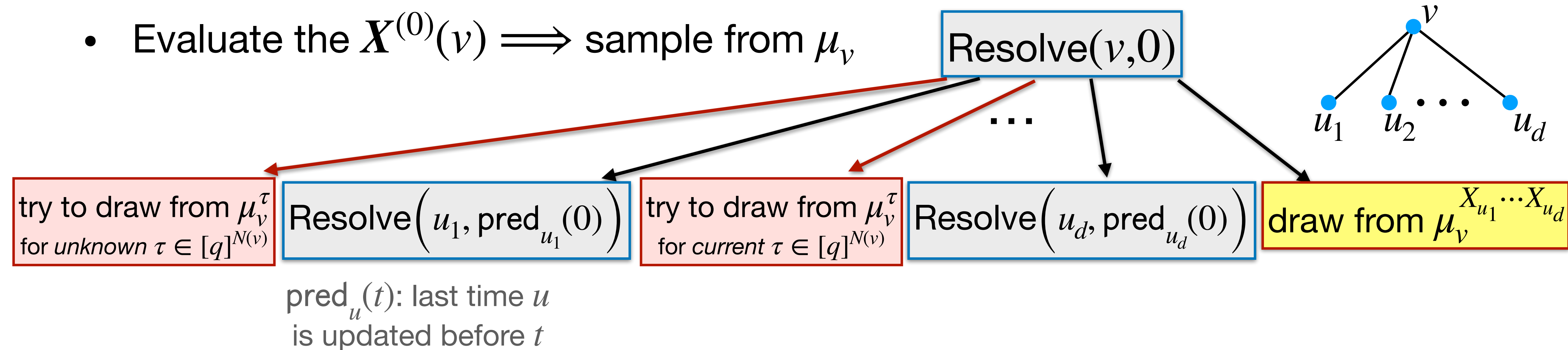
- pick $v \in V$ uniformly at random;
 - update the evaluation of X_v according to its marginal distribution $\mu_v(\cdot \mid X_{N(v)})$.
- For marginal sampler (which evaluates X_v^*):
It seems necessary to faithfully simulate everything...?

Marginal Sampler via *Backward Deduction*

- Imagine an idealized Glauber dynamics:

$$X^{(-\infty)} \rightarrow \dots \rightarrow X^{(-2)} \rightarrow X^{(-1)} \rightarrow X^{(0)} \sim \mu$$

- Evaluate the $X^{(0)}(v) \Rightarrow$ sample from μ_v



- [\[Feng-Guo-Wang-Wang-Y., FOCS 2023\]](#): with grand couplings, this terminates within $O(1)$ cost in expectation, and $O(\log n)$ cost with high probability

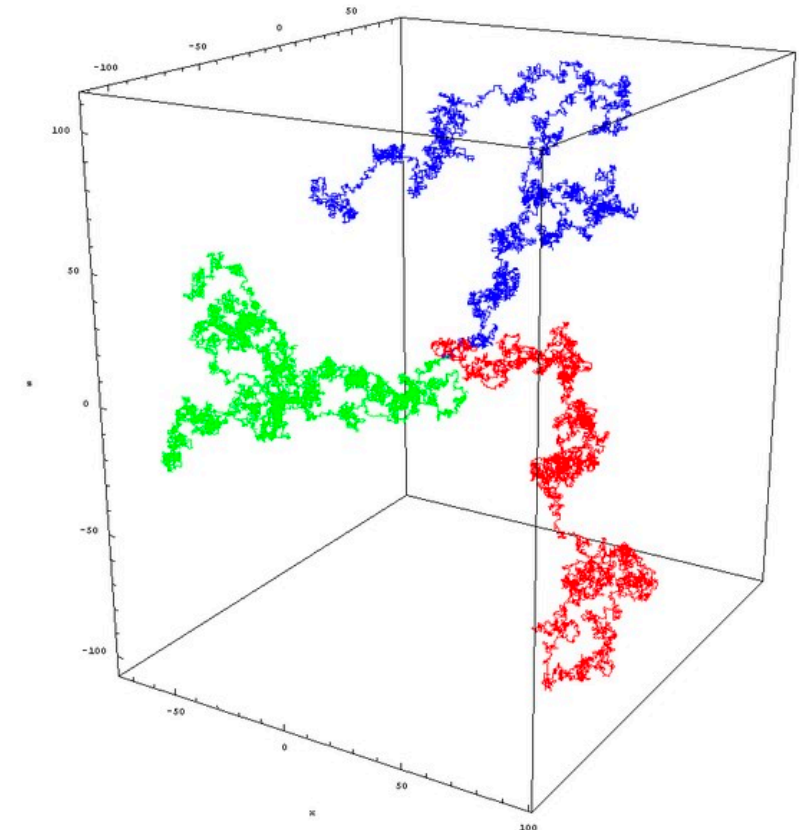
Dynamic Sampling

Dynamic Sampling problem: for dynamically changing distributions $\mu \rightarrow \mu'$



$$X \sim \mu \xrightarrow[\text{with incremental cost}]{\text{dynamic update}} X' \sim \mu'$$

- Sampling/inference tasks on dynamically changing data:
 - Online data, data streams, network environment, etc.
- Dynamically changing graphical models generated in:
 - Locally-iterative algorithms for learning.
 - Self-reduction procedure in approximate counting.



Classic random walks fail on dynamic data

- **Algorithmic Lipschitz:** transform $X \sim \mu$ to $X' \sim \mu'$ with cost proportional to $\text{diff}(\mu, \mu')$

Dynamic Sampling

Dynamic Sampling problem: for dynamically changing distributions $\mu \rightarrow \mu'$



$$X \sim \mu \xrightarrow[\text{with incremental cost}]{\text{dynamic update}} X' \sim \mu'$$

Algorithm 1: Dynamic Sampler

Input : a graphical model \mathcal{I} and a random sample $\mathbf{X} \sim \mu_{\mathcal{I}}$;
Update: an update (D, Φ_D) which modifies \mathcal{I} to \mathcal{I}' ;
Output: a random sample $\mathbf{X} \sim \mu_{\mathcal{I}'}$;

- 1 $\mathcal{R} \leftarrow \text{vbl}(D)$;
- 2 **while** $\mathcal{R} \neq \emptyset$ **do**
- 3 $(\mathbf{X}, \mathcal{R}) \leftarrow \text{Local-Resample}(\mathcal{I}', \mathbf{X}, \mathcal{R})$;
- 4 **return** \mathbf{X} ;

Algorithm 2: Local-Resample($\mathcal{I}, \mathbf{X}, \mathcal{R}$)

Input : a graphical model $\mathcal{I} = (V, E, [q], \Phi)$, a configuration $\mathbf{X} \in [q]^V$ and a $\mathcal{R} \subseteq V$;
Output: a new pair $(\mathbf{X}', \mathcal{R}')$ of configuration $\mathbf{X}' \in [q]^V$ and subset $\mathcal{R}' \subseteq V$;

- 1 for each $e \in E^+(\mathcal{R})$, in parallel, compute $\kappa_e \triangleq \frac{1}{\phi_e(\mathbf{X}_e)} \min_{x \in [q]^e: x_e \cap \mathcal{R} = \mathbf{X}_e \cap \mathcal{R}} \phi_e(x)$;
- 2 for each $v \in \mathcal{R}$, in parallel, resample $X_v \in [q]$ independently according to distribution ϕ_v ;
- 3 for each $e \in E^+(\mathcal{R})$, in parallel, sample $F_e \in \{0, 1\}$ ind. with $\Pr[F_e = 0] = \kappa_e \cdot \phi_e(\mathbf{X}_e)$;
- 4 $\mathbf{X}' \leftarrow \mathbf{X}$ and $\mathcal{R}' \leftarrow \bigcup_{e \in E: F_e = 1} e$;
- 5 **return** $(\mathbf{X}', \mathcal{R}')$.

- A dynamic sampling algorithm:
[\[Feng-Vishnoi-Y., STOC '19\]](#)
 - correct and efficient on *dynamic* data
 - *parallel, distributed, communication-efficient*
 - *Las Vegas* algorithm for *perfect* sampling

Summary

- Computational phase transition of sampling
- Parallel, marginal (modular), dynamic sampling
- Theme of future work:
 - a unified and critical theory for sampling and solving
 - classify efficient computing through efficient sampling
 - Turing (1936): “*What is computation?*”
by investigating Hilbert’s *Entscheidungsproblem*
 - In 2023: “*What is efficient (Monte Carlo) computation?*”
by classifying: “*What distributions are easy to sample?*”



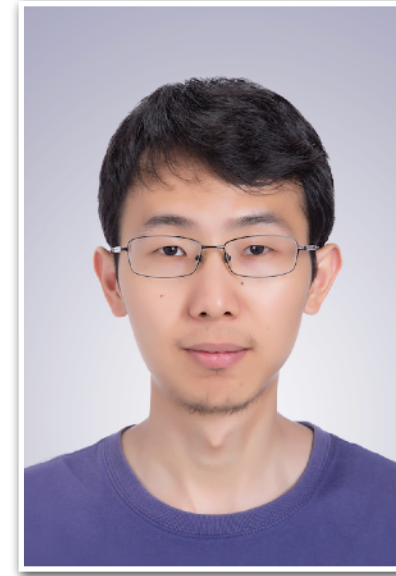
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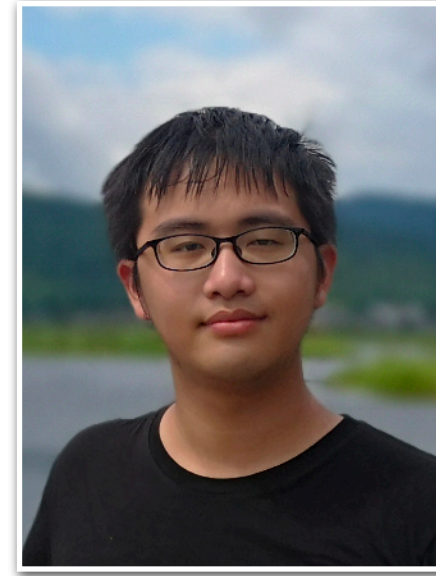
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- [\[Chen-Liu-Y. '23\]](#): Uniqueness and rapid mixing in the bipartite hardcore model. **FOCS '23**.
- [\[Feng-Guo-Wang-Wang-Y. '23\]](#): Towards derandomising Markov chain Monte Carlo. **FOCS '23**.
- [\[Chen-Feng-Y.-Zhang '22\]](#): Optimal mixing for two-state anti-ferromagnetic spin systems. **FOCS '22**.
- [\[He-Wang-Y. '22\]](#): Sampling Lovász local lemma for general constraint satisfaction solutions in near-linear time. **FOCS '22**.
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- [\[Feng-Guo-Y.-Zhang '20\]](#): Fast sampling and counting k -SAT solutions in the local lemma regime. **STOC '20**. **JACM '21**.
- [\[Feng-Vishnoi-Y. '19\]](#): Dynamic sampling from graphical models. **STOC '19**. **SICOMP '21**.
- [\[Efthymiou-Hayes-Štefankovič-Vigoda-Y. '16\]](#): Convergence of MCMC and loopy BP in the tree uniqueness region for the hardcore model. **FOCS '16**. **SICOMP '19**.

Thank you!

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